

1.

$$v_y = v_{lyt} + v_{rel y} = \frac{1}{2} b_0 t^2$$

$$y(t) = y(t_0) + \int_{t_0}^t v_y(t') dt' = -l + \int_0^t \frac{1}{2} b_0 t'^2 dt' =$$

$$= -l + \frac{1}{2} b_0 \left[\frac{t'^3}{3} \right]_0^t = -l + \frac{1}{6} b_0 t^3 \quad (*)$$

$$v_x = v_{lx} + v_{rel x} = v_0 \left(\frac{v_y}{l} + 1 \right) \left(1 - \frac{v_y^2}{l^2} \right) + a_0 t$$

$$x(t) = x(t_0) + \int_{t_0}^t v_x(t') dt' = \int_0^t \left(v_0 \left(\frac{v_y(t')}{l} + 1 \right) \left(1 - \frac{v_y(t')^2}{l^2} \right) + a_0 t' \right) dt' =$$

$$= \int_0^t \left(v_0 \left(\frac{-l + \frac{1}{6} b_0 t'^3}{l} + 1 \right) \left(1 - \frac{(-l + \frac{1}{6} b_0 t'^3)^2}{l^2} \right) + a_0 t' \right) dt' =$$

↑
*

$$= \int_0^t v_0 \frac{1}{6} \frac{b_0}{l} t'^3 \left(1 - 1 + \frac{1}{3} \frac{b_0}{l} t'^3 - \frac{1}{36} \frac{b_0^2}{l^2} t'^6 \right) dt' + \int_0^t a_0 t' dt' =$$

$$= \int_0^t \frac{1}{6} v_0 \frac{b_0}{l} \cdot \frac{1}{3} \frac{b_0}{l} t'^6 dt' - \int_0^t \frac{1}{6} v_0 \frac{b_0}{l} \cdot \frac{1}{36} \frac{b_0^2}{l^2} t'^9 dt' + \int_0^t a_0 t' dt' =$$

$$= \frac{1}{3 \cdot 6 \cdot 7} \frac{v_0 b_0^2}{l^2} t^7 - \frac{1}{6 \cdot 36 \cdot 10} \frac{v_0 b_0^3}{l^3} t^{10} + \frac{1}{2} a_0 t^2$$

Altdalmos
 útmutatás:
 olyan sorrendben
 számoljuk ki
 a $v_{rel y}(t)$ -t
 függvényeket,
 onnan kezdve
 a lehetséges.

$$\textcircled{*} \rightarrow t = \sqrt[3]{6 \frac{y+l}{b_0}}$$

$$\rightarrow x(y) \equiv x(t(y)) = \frac{1}{3 \cdot 6 \cdot 7} \frac{v_0 b_0^2}{l^2} \left(6 \frac{y+l}{b_0}\right)^{\frac{7}{3}} - \frac{1}{10 \cdot 6 \cdot 36} \frac{v_0 b_0^3}{l^3} \left(6 \frac{y+l}{b_0}\right)^{\frac{10}{3}} + \frac{1}{2} a_0 \left(6 \frac{y+l}{b_0}\right)^{\frac{2}{3}}$$

$$\begin{aligned} X \equiv x(y=l) &= \frac{1}{3 \cdot 6 \cdot 7} \frac{v_0 b_0^2}{l^2} \left(6 \frac{2l}{b_0}\right)^{\frac{7}{3}} - \frac{1}{6 \cdot 36 \cdot 10} \frac{v_0 b_0^3}{l^3} \left(6 \frac{2l}{b_0}\right)^{\frac{10}{3}} + \\ &+ \frac{1}{2} a_0 \left(6 \frac{2l}{b_0}\right)^{\frac{2}{3}} = \frac{2^{\frac{7}{3}} \cdot 6^{\frac{4}{3}}}{3 \cdot 7} \frac{v_0 l^{\frac{1}{3}}}{b_0^{\frac{1}{3}}} - \frac{2^{\frac{10}{3}} \cdot 6^{\frac{1}{3}}}{10} \frac{v_0 l^{\frac{1}{3}}}{b_0^{\frac{1}{3}}} + \\ &+ \frac{6^{\frac{2}{3}}}{2^{\frac{1}{3}}} a_0 \frac{l^{\frac{2}{3}}}{b_0^{\frac{2}{3}}} = \left(\frac{2^{\frac{7}{3}} \cdot 6^{\frac{4}{3}}}{3 \cdot 7} - \frac{2^{\frac{10}{3}} \cdot 6^{\frac{1}{3}}}{10} \right) \frac{v_0 l^{\frac{1}{3}}}{b_0^{\frac{1}{3}}} + \frac{6^{\frac{2}{3}}}{2^{\frac{1}{3}}} \frac{a_0 l^{\frac{2}{3}}}{b_0^{\frac{2}{3}}} \end{aligned}$$

2. $t_0 = 0$, $v(t=0) = v_0$, $\varphi(t=0) = 0$

$$v_{\varphi} = 0 \Rightarrow \omega_{\varphi} \equiv \dot{\varphi} = \frac{v_{\varphi}}{r} = 0 \text{ minden } r \text{ mellett}$$

$$\dot{\psi} = \dot{\varphi} + \dot{\varphi}_{\text{rel}} = 0 + \omega_0 = \omega_0$$

$$\varphi(t) = \varphi(t_0) + \int_{t_0}^t \dot{\varphi}(t') dt' = 0 + \int_0^t \omega_0 dt' = \omega_0 t \quad (*)$$

$$v_r = v_{\varphi} r = v_0 \left(1 - \frac{(\varphi - \pi/8)^2}{(\pi/8)^2} \right)$$

↑
relatív mozgás miatt

$$v(t) = v(t_0) + \int_{t_0}^t v_r(t') dt' = v_0 + \int_0^t v_0 \left(1 - \frac{(\varphi(t') - \pi/8)^2}{(\pi/8)^2} \right) dt' =$$

$$= v_0 + \int_0^t v_0 \left(1 - \frac{(\omega_0 t' - \pi/8)^2}{(\pi/8)^2} \right) dt' = v_0 +$$

↑
(*)

$$+ v_0 \int_0^t \left(\frac{8}{\pi} \omega_0^2 t'^2 + \frac{16}{\pi} \omega_0 t' \right) dt' = v_0 + v_0 \left(-\frac{64}{3\pi^2} \omega_0^2 t^3 + \right.$$

$$\left. + \frac{8}{\pi} \omega_0 t^2 \right)$$

$$(*) \rightarrow t = \frac{\varphi}{\omega_0}$$

$$\rightarrow v(\varphi) \equiv v(t(\varphi)) = v_0 + v_0 \left(\frac{8}{\pi} \omega_0 \frac{\varphi^2}{\omega_0^2} - \frac{64}{3\pi^2} \omega_0^2 \frac{\varphi^3}{\omega_0^3} \right)$$

$$R = v(\varphi = \frac{\pi}{4}) = v_0 + \frac{v_0}{\omega_0} \left(\frac{8}{\pi} \cdot \frac{\pi^2}{4^2} - \frac{64}{3\pi^2} \cdot \frac{\pi^3}{4^3} \right) =$$

$$= v_0 + \frac{v_0}{\omega_0} \left(\frac{\pi}{2} - \frac{\pi}{3} \right) = v_0 + \frac{\pi}{6} \frac{v_0}{\omega_0}$$

3.

$$v_x = v_{fx} + v_{relx} = v_0 + \frac{1}{2} b_0 t^2 - v_0 = \frac{1}{2} b_0 t^2$$

$$x(t) = x(t_0) + \int_{t_0}^t v_x(t') dt' = \int_0^t \frac{1}{2} b_0 t'^2 dt' = \frac{1}{6} b_0 t^3$$

$$a_{xy} = a_{fx} + a_{relx} = 0 + a_0 \frac{x^2}{l^2} = a_0 \frac{x^2}{l^2}$$

$$v_{xy}(t) = v_{xy}(t_0) + \int_{t_0}^t a_{xy}(t') dt' = \int_0^t a_0 \frac{x(t')^2}{l^2} dt' =$$

$$= \int_0^t a_0 \frac{1}{6^2} b_0^2 t'^6 \frac{1}{l^2} dt' = \frac{1}{7 \cdot 6^2} \frac{a_0 b_0^2}{l^2} t^7$$

$$y(t) = y(t_0) + \int_{t_0}^t v_{xy}(t') dt' = -l + \int_0^t \frac{1}{7 \cdot 6^2} \frac{a_0 b_0^2}{l^2} t'^7 dt' =$$

$$= -l + \frac{1}{8 \cdot 7 \cdot 6^2} \frac{a_0 b_0^2}{l^2} t^8$$

$$\rightarrow t(y) = \sqrt[8]{8 \cdot 7 \cdot 6^2 \frac{(y+l)l^2}{a_0 b_0^2}}, \quad t(y=l) = \sqrt[8]{8 \cdot 7 \cdot 6^2 \frac{l^3}{a_0 b_0^2}}$$

$$X = x(t(y=l)) = \frac{1}{6} b_0 \left(8 \cdot 7 \cdot 6^2 \frac{l^3}{a_0 b_0^2} \right)^{3/8} =$$

$$= \frac{1}{6} b_0 \left(2^6 \cdot 3^2 \cdot 7 \frac{l^3}{a_0 b_0^2} \right)^{3/8}$$

4.

$$\dot{\varphi}(t) = \frac{v_{\varphi}(t)}{r(t)} = \frac{v_{\text{rel}\varphi}(t) + v_{\text{rel}r}(t)}{r(t)} =$$

$$= \frac{0 + \mu_1 \frac{r(t)}{R_1}}{r(t)} = \frac{\mu_1}{R_1}$$

$$\varphi(t) = \varphi(t_0) + \int_{t_0}^t \frac{v_{\varphi}(t')}{r(t')} dt' = \varphi(t_0) + \int_{t_0}^t \frac{\mu_1}{R_1} dt' =$$

$$= 0 + \int_0^t \frac{\mu_1}{R_1} dt' = \frac{\mu_1 t}{R_1}$$

$$v_r = v_{\text{rel}r} + v_{\text{rel}\varphi} = v_0 \sin^2 \varphi + a_0 t$$

$$r(t) = r(t_0) + \int_{t_0}^t v_r(t') dt' = R_1 + \int_0^t (v_0 \sin^2 \varphi(t') + a_0 t') dt' =$$

$$= R_1 + \int_0^t (v_0 \sin^2 \left(\frac{\mu_1 t'}{R_1} \right) + a_0 t') dt' =$$

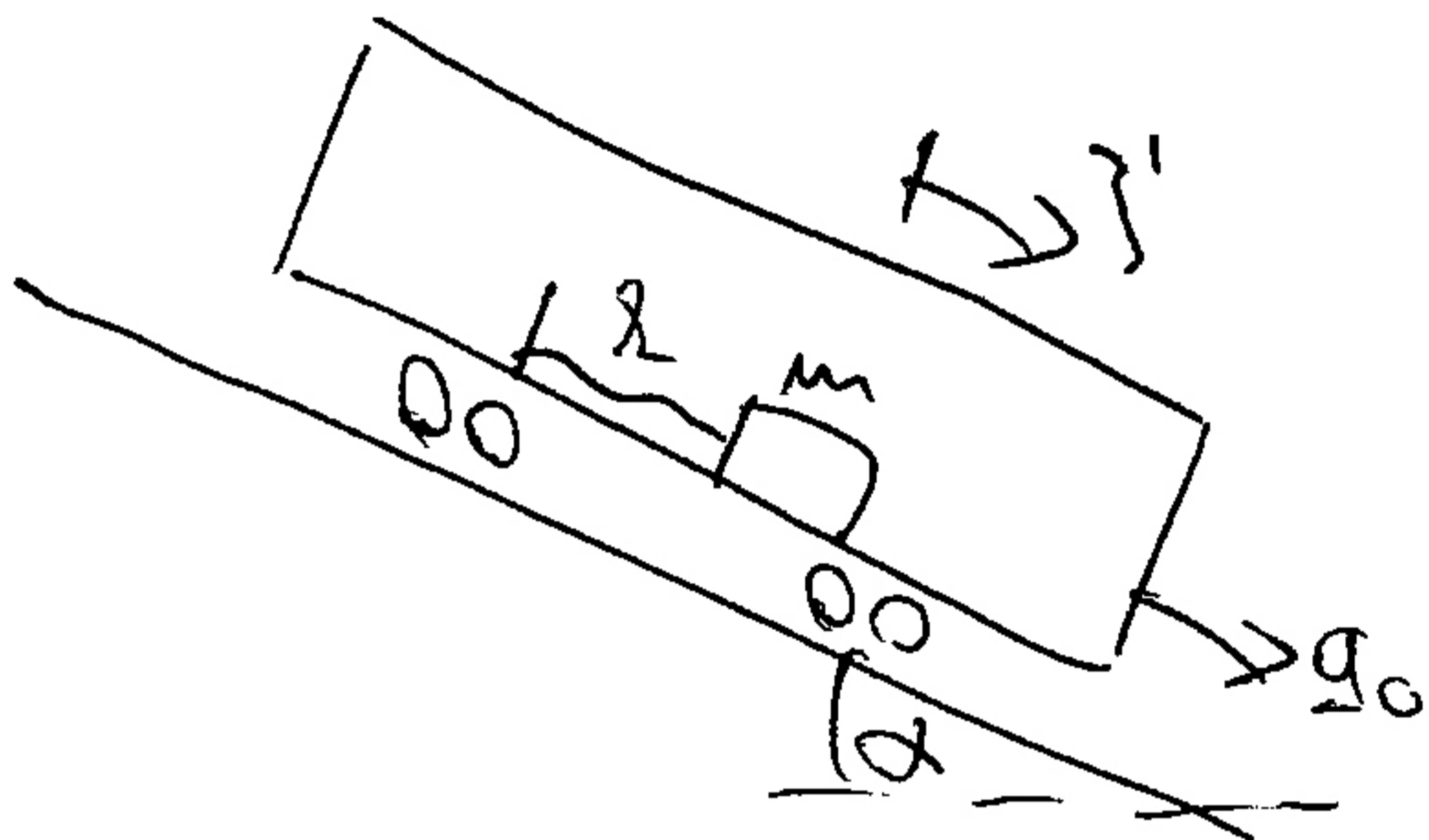
$$= R_1 + \int_0^t \left(\frac{v_0}{2} - \frac{v_0}{2} \cos \left(\frac{2\mu_1 t'}{R_1} \right) + a_0 t' \right) dt' =$$

$$= R_1 + \left[\frac{v_0 t'}{2} - \frac{v_0}{2} \cdot \frac{R_1}{2\mu_1} \sin \left(\frac{2\mu_1 t'}{R_1} \right) + \frac{1}{2} a_0 t'^2 \right]_0^t =$$

$$= R_1 + \frac{v_0 t}{2} + \frac{1}{2} a_0 t^2 - \frac{v_0 R_1}{4\mu_1} \sin \left(\frac{2\mu_1 t}{R_1} \right)$$

EMB/Gy1/06

5.



b)

$$\ddot{z}' = 0$$

→

$$0 = -\lambda z'^* + mg \sin \alpha - m a_0$$

~~$$z'^* = \frac{m(g \sin \alpha - a_0)}{\lambda}$$~~

$$z'^* = \frac{m(g \sin \alpha - a_0)}{\lambda}$$

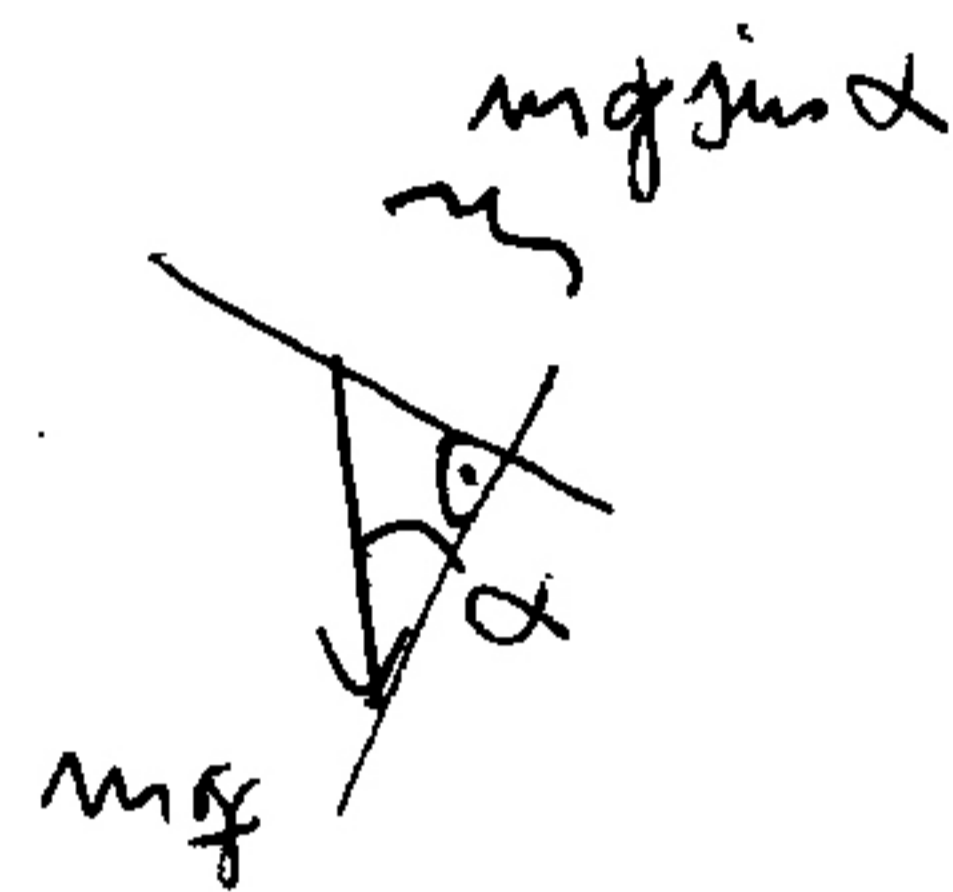
a)

$$(m \ddot{z}')_{||} = (F_{\text{spring}})_{||} + (mg)_{||} - (m a_0)_{||}$$

$$(m \ddot{z}')_{||} = m \ddot{z}'$$

$$(F_{\text{spring}})_{||} = -\lambda z'$$

$$(mg)_{||} = mg \sin \alpha$$



$$(-m a_0)_{||} = -m a_0$$

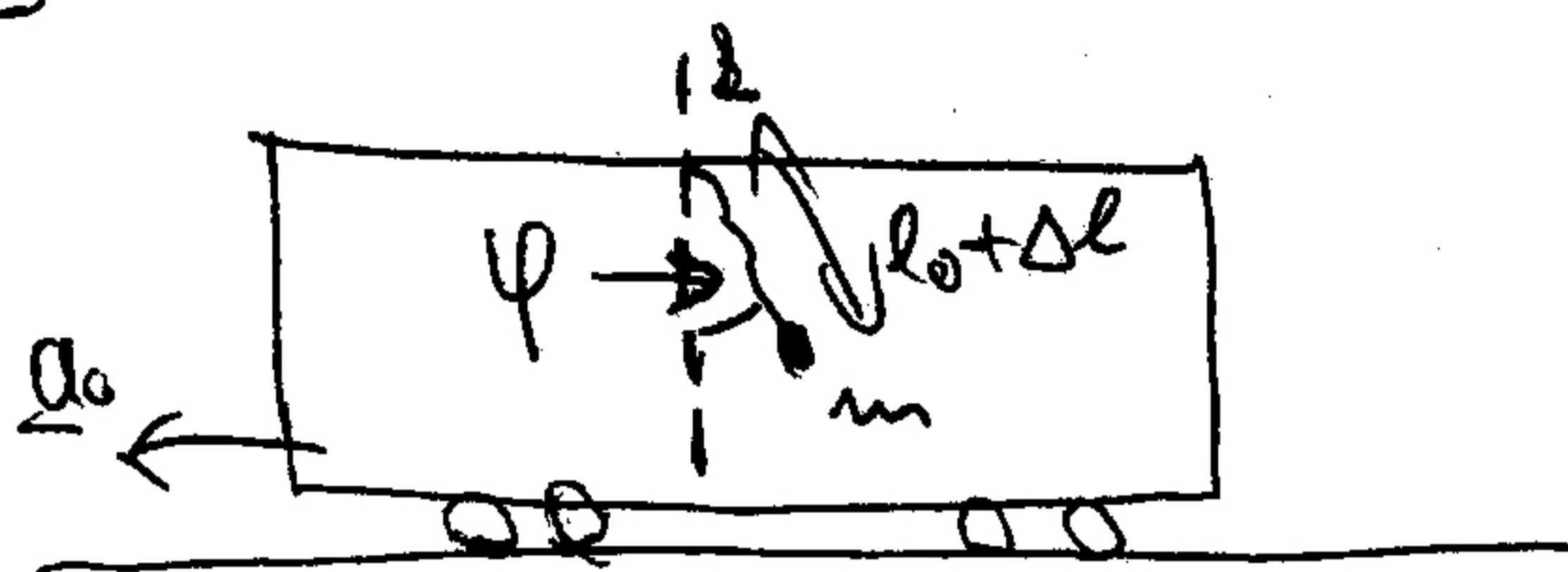
→

$$m \ddot{z}' = -\lambda z' + mg \sin \alpha - m a_0$$

6.

EMB/Gy1/07

$\varphi^* \Rightarrow \Delta l^* \Rightarrow$



$$m \ddot{\underline{v}}' = \underline{F}_{mg} + m \underline{g} - m \underline{g}_0$$

$$(m \ddot{\underline{v}}')_{x'} = m \ddot{x}'$$

$$(m \ddot{\underline{v}}')_{y'} = m \ddot{y}'$$

$$(mg)_{x'} = 0$$

$$(mg)_{y'} = -mg$$

$$(-ma_0)_{x'} = ma_0$$

$$(-ma_0)_{y'} = 0$$

$$\rightarrow m \ddot{x}' = -2 \Delta l \sin \varphi + ma_0$$

$$m \ddot{y}' = 2 \Delta l \cos \varphi - mg$$

$$\ddot{x}' = 0, \ddot{y}' = 0$$

$$\rightarrow 0 = -2 \Delta l^* \sin \varphi^* + ma_0 \quad \nearrow$$

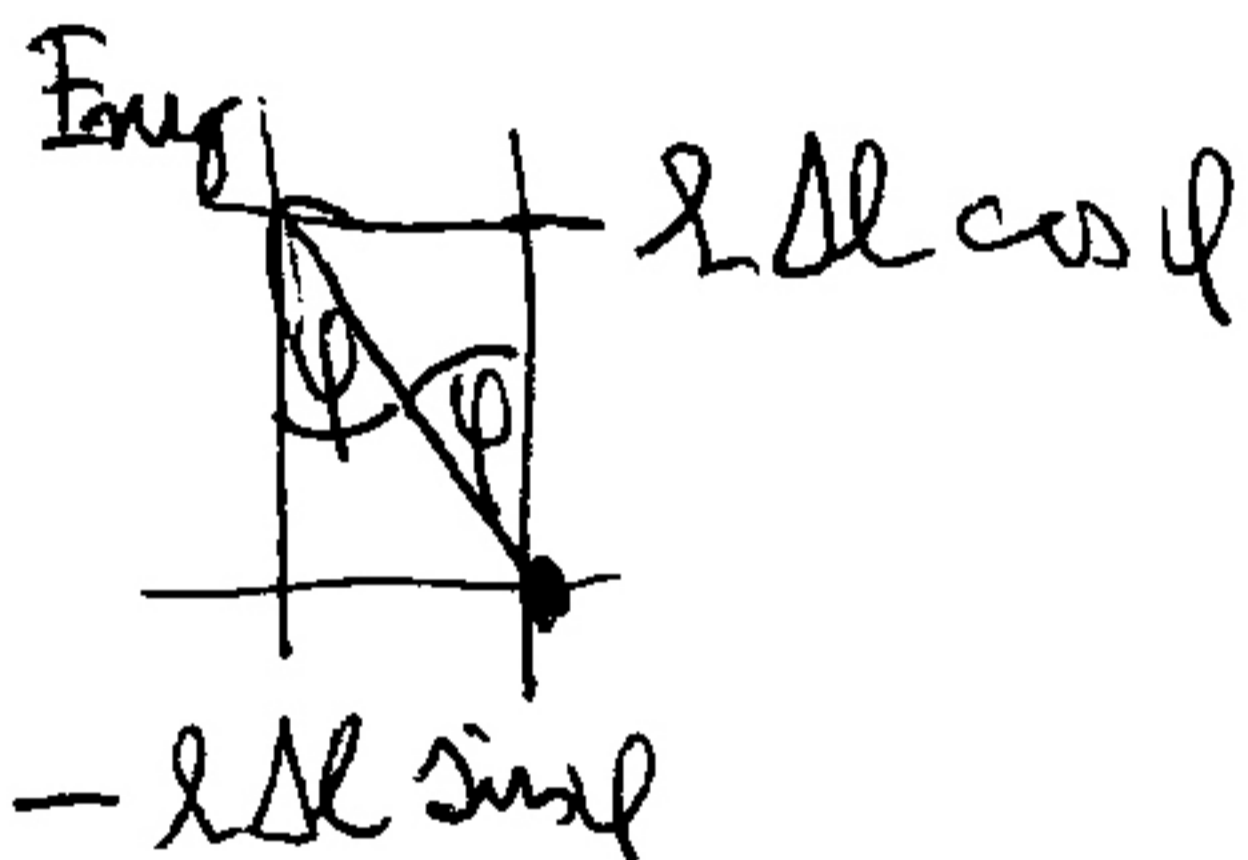
$$0 = 2 \Delta l^* \cos \varphi^* - mg$$

$$\frac{2 \Delta l^* \sin \varphi^*}{2 \Delta l^* \cos \varphi^*} = \frac{ma_0}{mg}, \quad \tan \varphi^* = \frac{a_0}{g}, \quad \varphi^* = \arctan \frac{a_0}{g}$$

$$(F_{mg})_{x'} = -2 \Delta l \sin \varphi$$

$$(F_{mg})_{y'} = +2 \Delta l \cos \varphi$$

for $\Delta l > 0$:



$\Delta l < 0$ - no handle

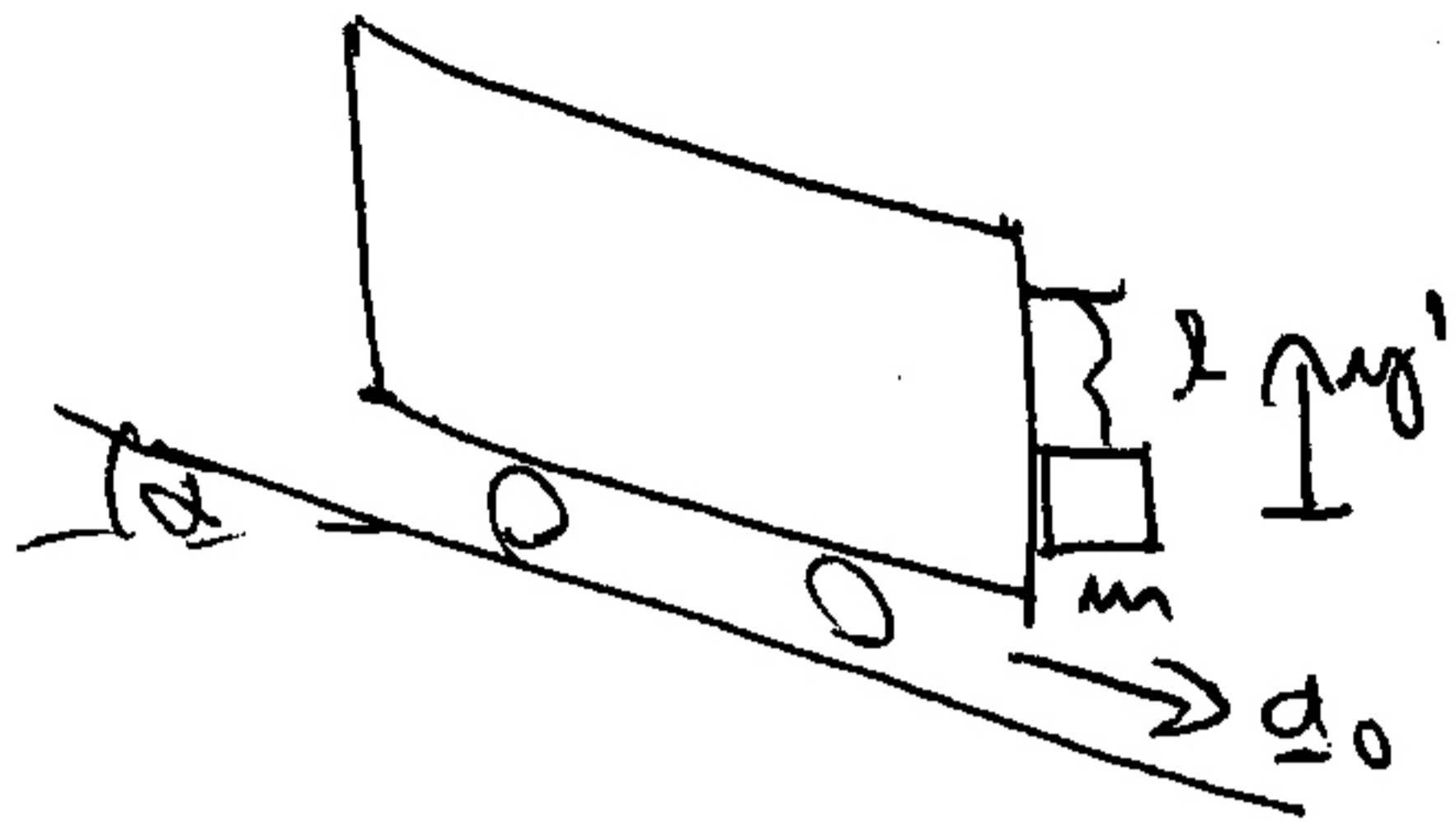
$$2 \Delta l^* (\sin^2 \varphi^* + \cos^2 \varphi^*) = 1$$

$$= m^2 a_0^2 + m^2 g^2$$

$$\Delta l^* = \frac{m \sqrt{a_0^2 + g^2}}{2}$$

EMB/Gg 1/08

7.



b)

$$\ddot{y} = 0$$

→

$$0 = -2\mu g + m g + m a_0 \sin \alpha$$

$$\ddot{y} \neq 0 \Rightarrow a_0 \neq ?$$

→

$$0 = -\mu g + \mu a_0 \sin \alpha$$

$$a_0 = \frac{g}{\sin \alpha}$$

a)

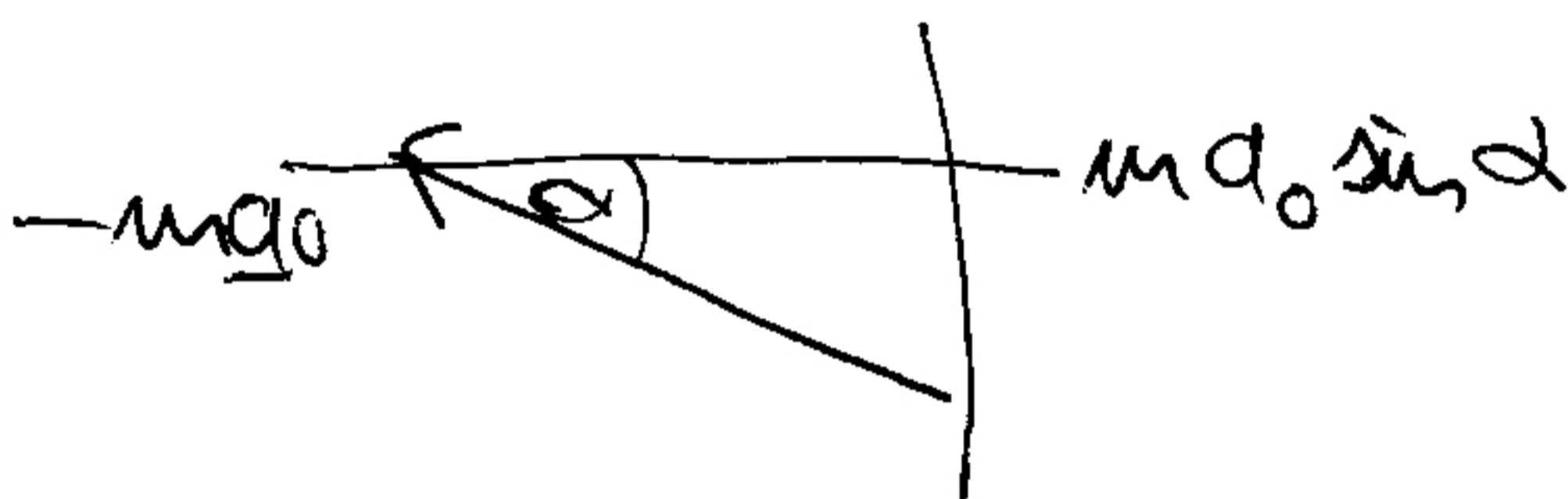
$$(m \ddot{v})_{||} = (F_{mg})_{||} + (mg)_{||} - (m a_0)_{||}$$

$$(m \ddot{v})_{||} = m \ddot{y}$$

$$(F_{mg})_{||} = -2\mu g$$

$$(mg)_{||} = -m g$$

$$(-m a_0)_{||} = m a_0 \sin \alpha$$

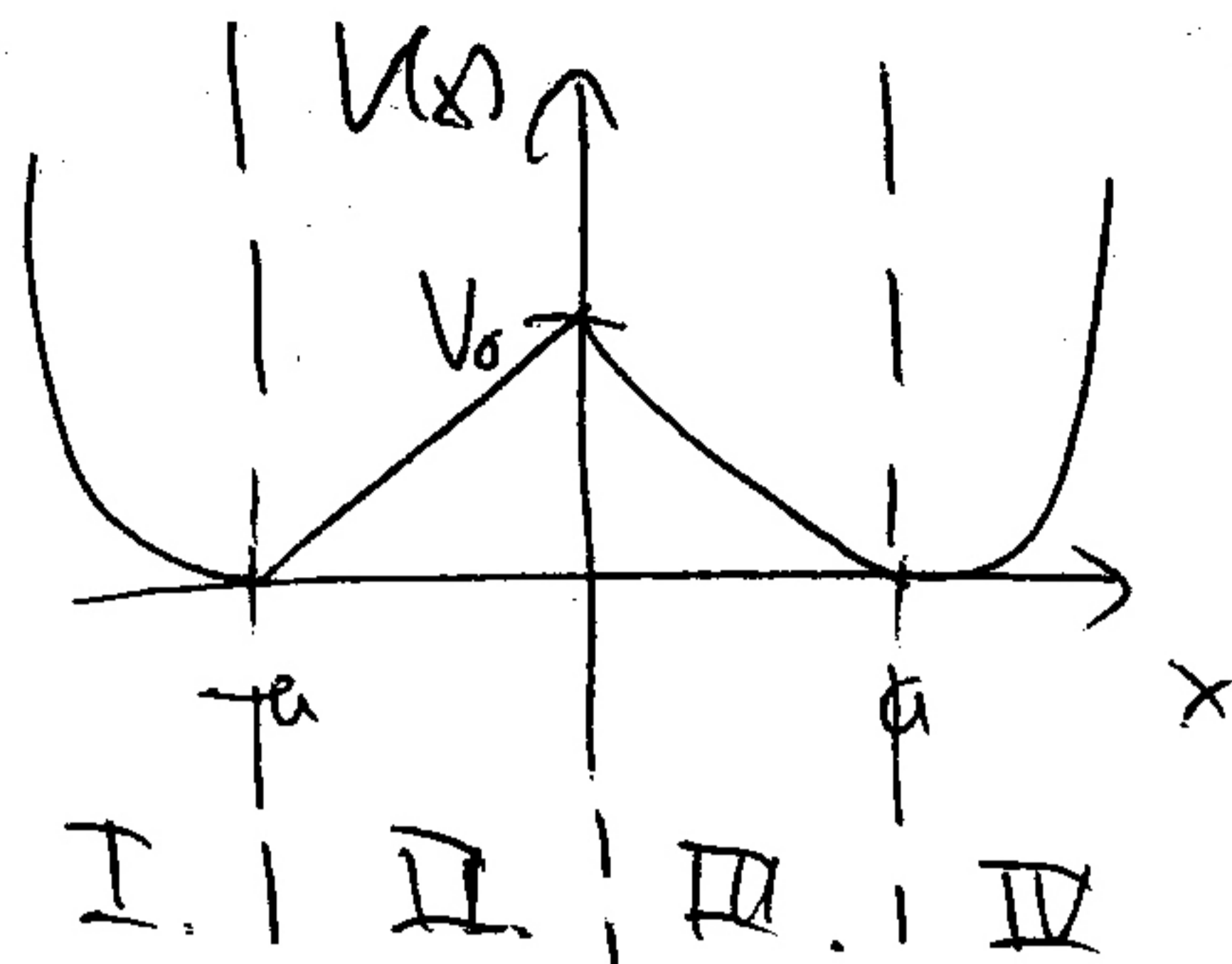


→

$$m \ddot{y} = -2\mu g - m g + m a_0 \sin \alpha$$

8.

$$V(x) = \begin{cases} \frac{1}{2} k(x+a)^2, & \text{ha } x < -a \\ V_0 \left(1 - \frac{|x|}{a}\right), & \text{ha } |x| \leq a \\ \frac{1}{2} k(x-a)^2, & \text{ha } x > a \end{cases}$$



• fordulópontok: $E = V(x_{fp})$

I.

$$E = \frac{1}{2} k(x_{fp1} + a)^2$$

$$\rightarrow x_{fp1} = -a - \sqrt{\frac{2E}{k}}$$

E az 1 negatív, van a) és b) esetben is, ugyanis $-a + \sqrt{\frac{2E}{k}} \notin I$.
Semmilyen E mellett.

- a) x_{fp1} valóban létezik.
b) x_{fp1} valóban létezik.

III.

$$E = V_0 \left(1 - \frac{x_{fp3}}{a}\right)$$

$$\rightarrow x_{fp3} = a \left(1 - \frac{E}{V_0}\right)$$

- a) $x_{fp3} \in III$,
valóban létezik.

- b) $x_{fp3} \notin III$, így
nem létezik.

II.

$$E = V_0 \left(1 + \frac{x_{fp2}}{a}\right)$$

$$\rightarrow x_{fp2} = a \left(\frac{E}{V_0} - 1\right)$$

- a) $x_{fp2} < 0$, így $x_{fp2} \in II$,
valóban létezik.

- b) $x_{fp2} > 0$, így $x_{fp2} \notin II$,
azaz nem valóban meglévő.

IV.

$$E = \frac{1}{2} k(x_{fp4} - a)^2$$

$$\rightarrow x_{fp4} = a + \sqrt{\frac{2E}{k}}$$

E az 1 negatív, van a) és b) esetben is, ugyanis $a - \sqrt{\frac{2E}{k}} < a$,
így $a - \sqrt{\frac{2E}{k}} \notin IV$. Semmilyen E mellett.

- a) és b) esetben is: x_{fp4}
valóban létezik.

• *egyenlet:*

I. $\frac{1}{2} m \dot{x}^2 + \frac{1}{2} k(x+a)^2 = E$ ellipszis

II. $\frac{1}{2} m \dot{x}^2 + V_0(1 + \frac{x}{a}) = E$ felül parabola

III. $\frac{1}{2} m \dot{x}^2 + V_0(1 - \frac{x}{a}) = E$ lefelé parabola

IV. $\frac{1}{2} m \dot{x}^2 + \frac{1}{2} k(x-a)^2 = E$ ellipszis

$\dot{x}(x=-a) = \pm \sqrt{\frac{2}{m} (E - V_0(1 + \frac{-a}{a}))} = \pm \sqrt{\frac{2E}{m}}$

a) és b) esetben is megegyelnek.

$\dot{x}(x=0) = \pm \sqrt{\frac{2}{m} (E - V_0(1 + \frac{0}{a}))} = \pm \sqrt{\frac{2}{m} (E - V_0)}$

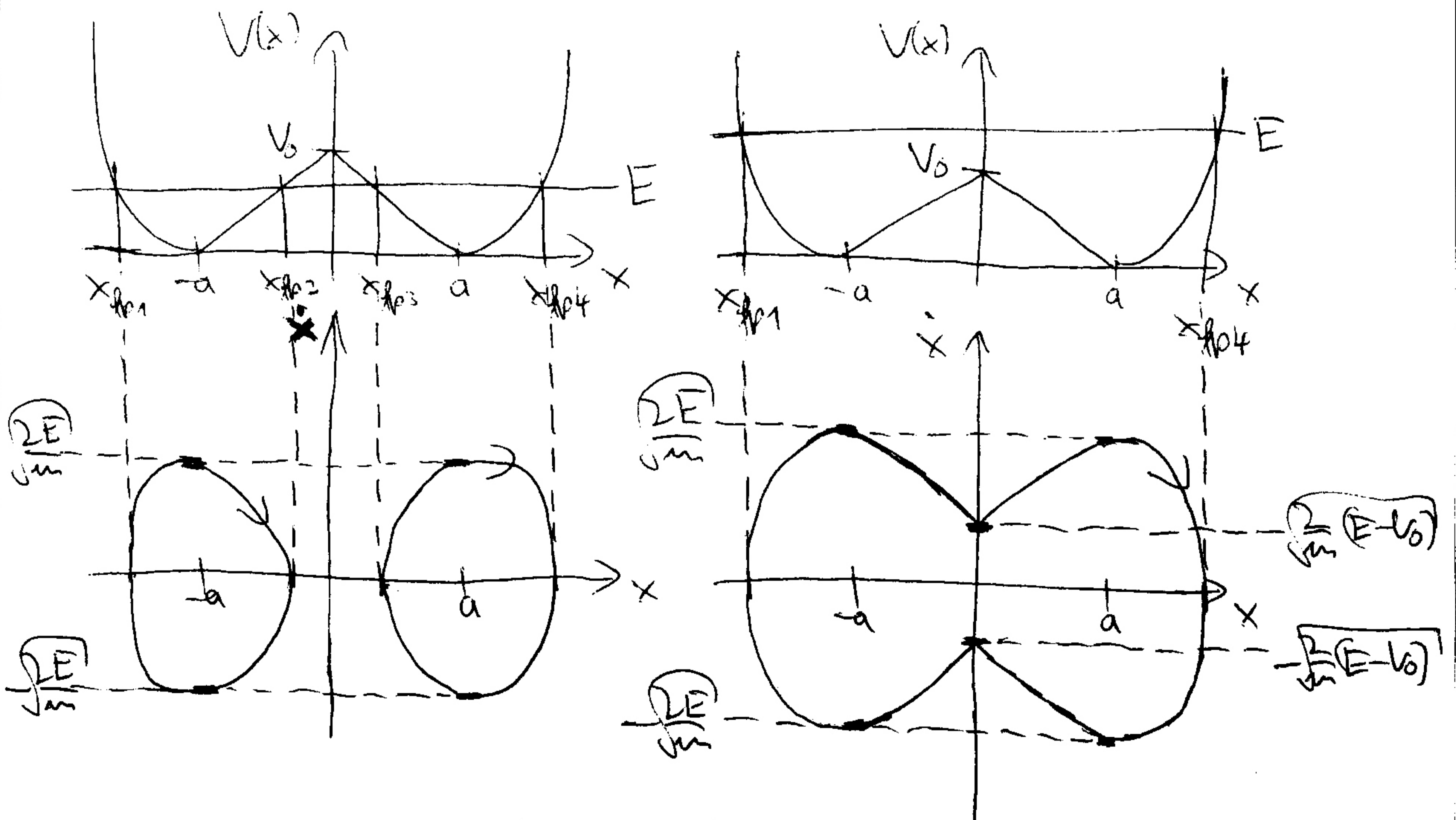
(csak b) esetben különböznek meg!

$\dot{x}(x=a) = \pm \sqrt{\frac{2}{m} (E - V_0(1 - \frac{a}{a}))} = \pm \sqrt{\frac{2E}{m}}$

a) és b) esetben is megegyelnek.

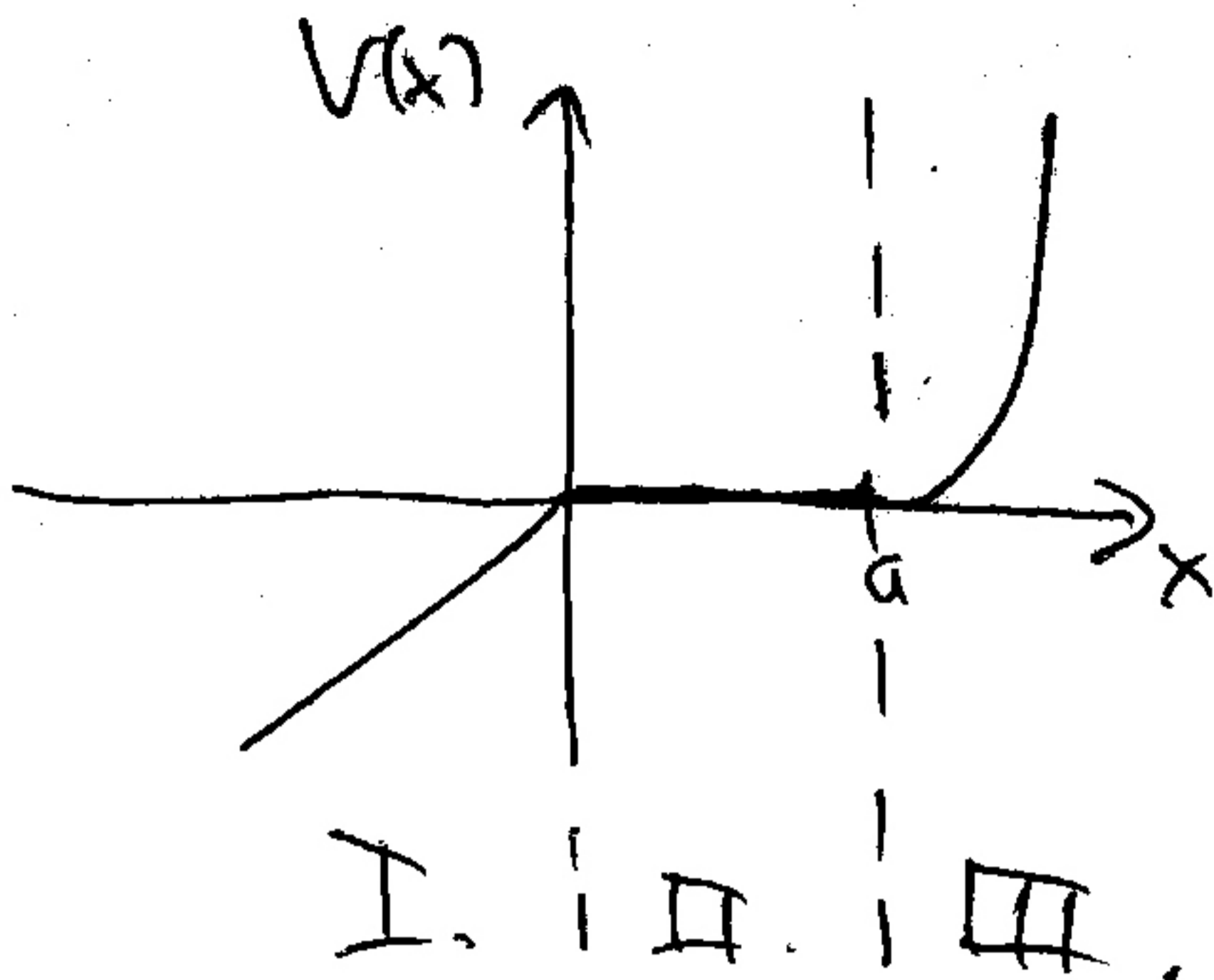
a)

b)



9.

$$V(x) = \begin{cases} \alpha x, & \text{ha } x < 0 \\ 0, & \text{ha } 0 \leq x < a \\ \frac{1}{2} \alpha (x-a)^2, & \text{ha } x \geq a \end{cases}$$



• fordulópontok: $E = V(x_{fp})$

I.

$$E = \alpha x_{fp1}$$

$$\rightarrow x_{fp1} = \frac{E}{\alpha}$$

- a) $x_{fp1} < 0$, így $x_{fp1} \notin I$, vagyis
 b) $x_{fp1} > 0$, azaz $x_{fp1} \notin I$,
 így nem valósul meg.

II.

$$E = 0$$

Teljesen az $E=0$ feltételt
 vizsgálva arra, hogy
 a II. tartományban
 legyen fordulópont.
 Ha ez teljesül, akkor
 a III. tartomány
 minden pontja kielégíti
 a fordulópontokra vonatkozó
 feltételt. Azonban
 az $E=0$ eset vizsgálata
 nem elegendő a feladatra
 a válasz színt.

III.

$$E = \frac{1}{2} \alpha (x_{fp2} - a)^2$$

$$\rightarrow x_{fp2} = a + \sqrt{\frac{2E}{\alpha}}$$

Elvileg lenne egy $x_{fp} = a - \sqrt{\frac{2E}{\alpha}}$
 megoldás is, de $a - \sqrt{\frac{2E}{\alpha}} < a$,
 vagyis $a - \sqrt{\frac{2E}{\alpha}} \notin III$. Semmilyen
 E mellett. Így tehát csak
 $x_{fp2} = a + \sqrt{\frac{2E}{\alpha}}$ lehet.

- a) $E < 0 \Rightarrow x_{fp2}$ nem valós, ami azt jelenti, hogy x_{fp2} nem létezik
 b) $E > 0 \Rightarrow x_{fp2}$ valós, ~~ami azt jelenti~~ mivel $x_{fp2} \in III$,
 x_{fp2} valóban létezik.

• egyenlet:

I. $\frac{1}{2} m \dot{x}^2 + \alpha x = E$ \checkmark parabola

II. $\frac{1}{2} m \dot{x}^2 = E$, állandó sebesség: $\dot{x} = \pm \sqrt{\frac{2E}{m}}$

Tudat a II. intervallumban az $\dot{x}(x)$ függvény konstans, azaz vízszintes egyenes.

III. $\frac{1}{2} m \dot{x}^2 + \frac{1}{2} k(x-a)^2 = E$
ellipszis

$\dot{x}(x > 0) = \pm \sqrt{\frac{2}{m}(E - 0)} = \pm \sqrt{\frac{2E}{m}}$

a főtérbeli trajektória (Mivel $0 \in \text{II.}$, ~~azaz~~ alapjában est már adott.)

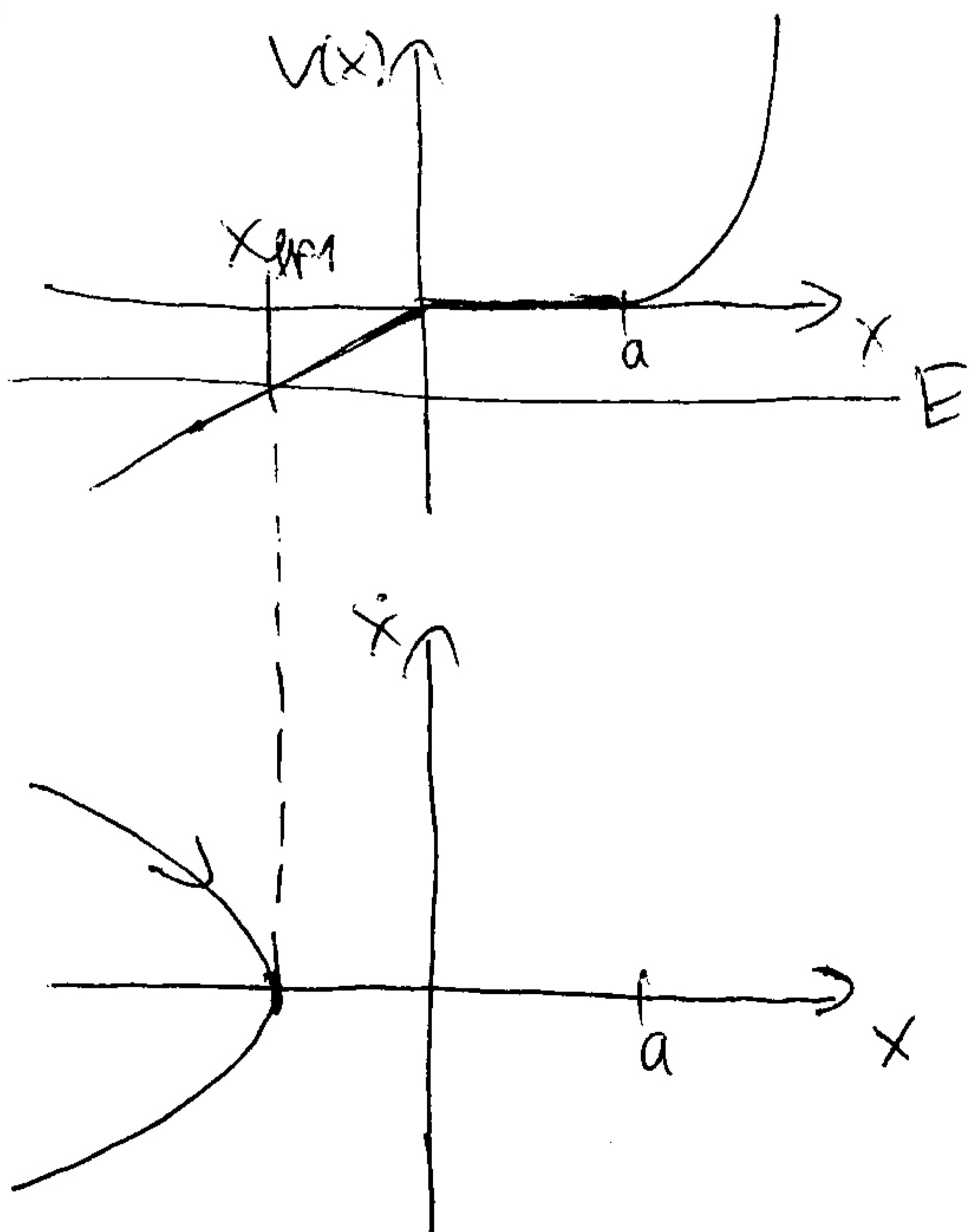
$\dot{x}(x=a) = \pm \sqrt{\frac{2}{m}(E - \frac{1}{2}k \cdot (a-a)^2)} =$

$= \pm \sqrt{\frac{2}{m}(E - 0)} = \pm \sqrt{\frac{2E}{m}}$

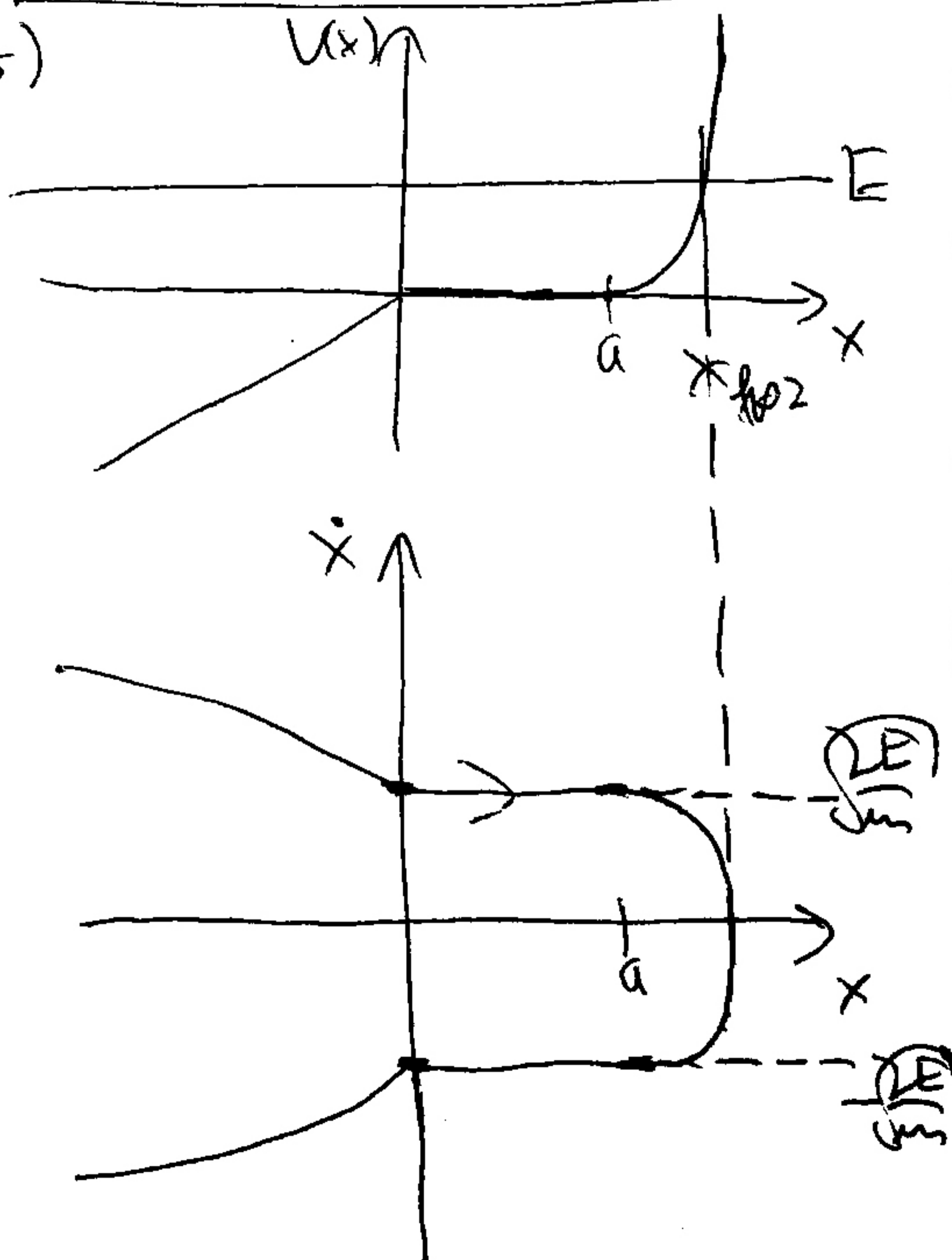
Mindkét korlátot teljesít csak b) esetben valóban meg!

(Mivel $V(x)$ költséges, és $x=a$ a II. intervallum vége-határánál, a főtérbeli trajektória egyenlete alapjában est is adott.)

a)



b)



10.

EMB/Gy1/13

$$V(x) = \begin{cases} -\alpha x - V_0 & , \text{ha } x \leq 0 \\ -V_0 \cos \frac{\pi x}{2a} & , \text{ha } 0 < x < a \\ \frac{1}{2} \alpha (x-a)^2 & , \text{ha } x > a \end{cases} \quad \alpha, V_0, a, \hbar > 0$$

$$-V_0 < E < 0$$

• ρ_{p1} :

I. $E = V(x_{\rho p1})$

$$E = -\alpha x_{\rho p1} - V_0$$

$$x_{\rho p1} = -\frac{V_0 + E}{\alpha}$$

$x_{\rho p1} < 0 \Rightarrow x_{\rho p1} \in I$.
 Így $x_{\rho p1}$ megvalósul

II. $E = V(x_{\rho p2})$

$$E = -V_0 \cos \frac{\pi x_{\rho p2}}{2a}$$

$$\frac{\pi x_{\rho p2}}{2a} = \arccos\left(-\frac{E}{V_0}\right)$$

$$x_{\rho p2} = \frac{2a}{\pi} \arccos\left(-\frac{E}{V_0}\right)$$

$$E < 0 \Rightarrow \arccos\left(-\frac{E}{V_0}\right) < \frac{\pi}{2}$$

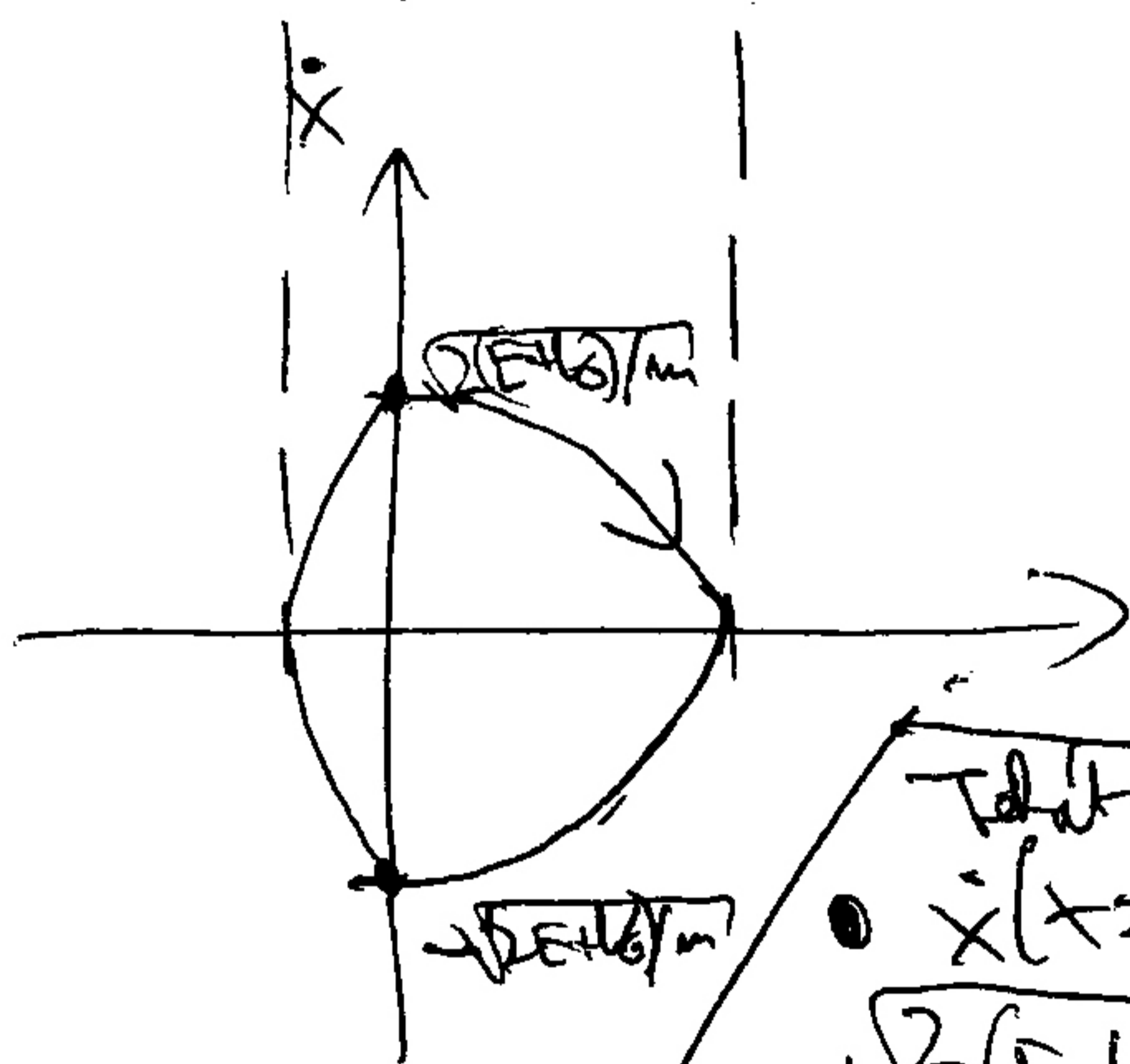
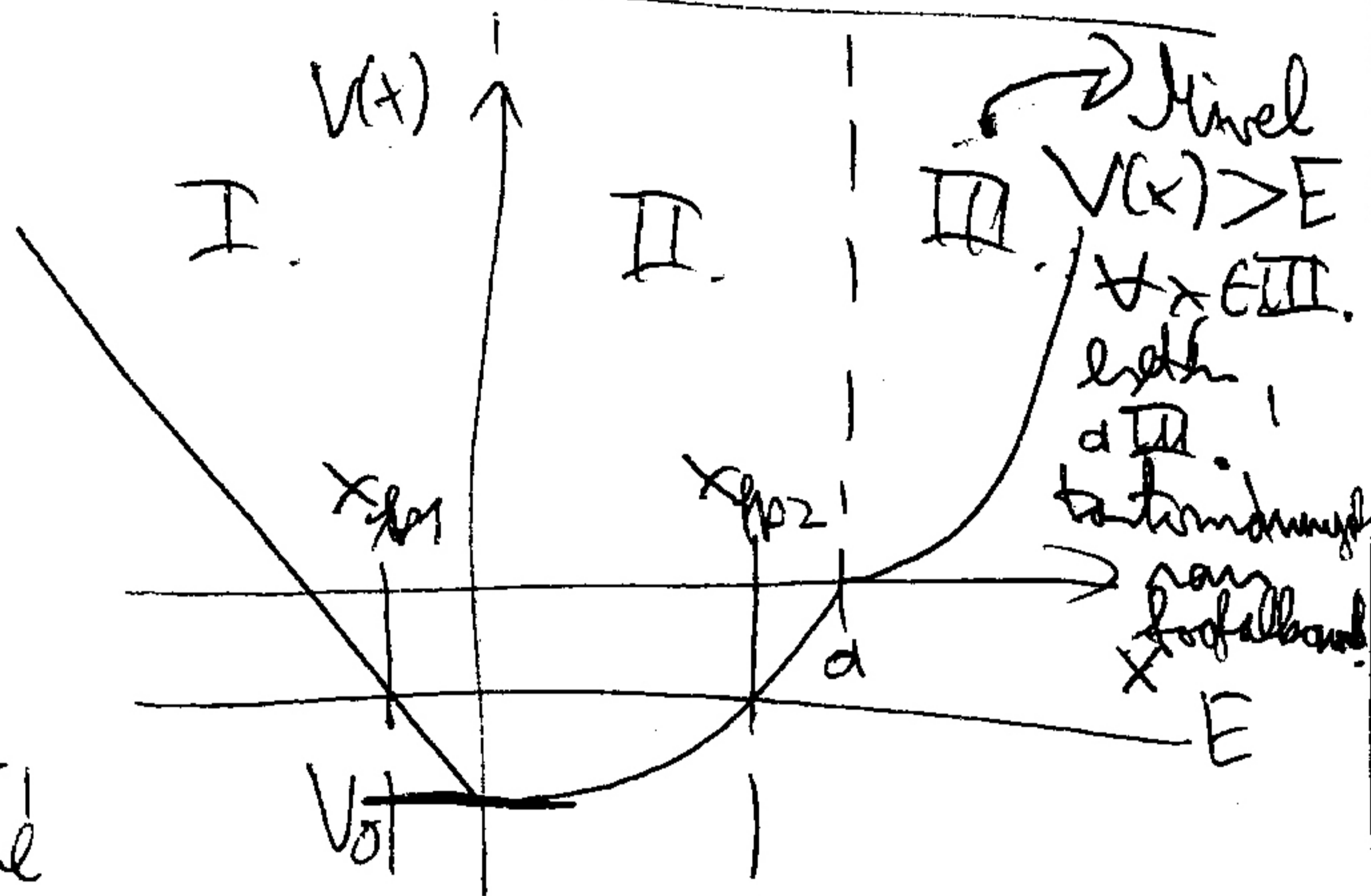
$$\Rightarrow \frac{2a}{\pi} \arccos\left(-\frac{E}{V_0}\right) < \frac{2a\pi}{\pi \cdot 2} = a$$

Ugyanakkor nyilván $x_{\rho p2} > 0$.

Így $x_{\rho p2} \in II$, $x_{\rho p2}$ megvalósul.

• egyenlet: I. $E = -\alpha x - V_0 + \frac{1}{2} m \dot{x}^2$

II. $E = -V_0 \cos \frac{\pi x}{2a} + \frac{1}{2} m \dot{x}^2$



Időt megvalósul.

$$\dot{x}(x=0) = \pm \sqrt{\frac{2}{m}(E - V(x=0))} = \pm \sqrt{\frac{2}{m}(E + V_0)} \in \mathbb{R},$$

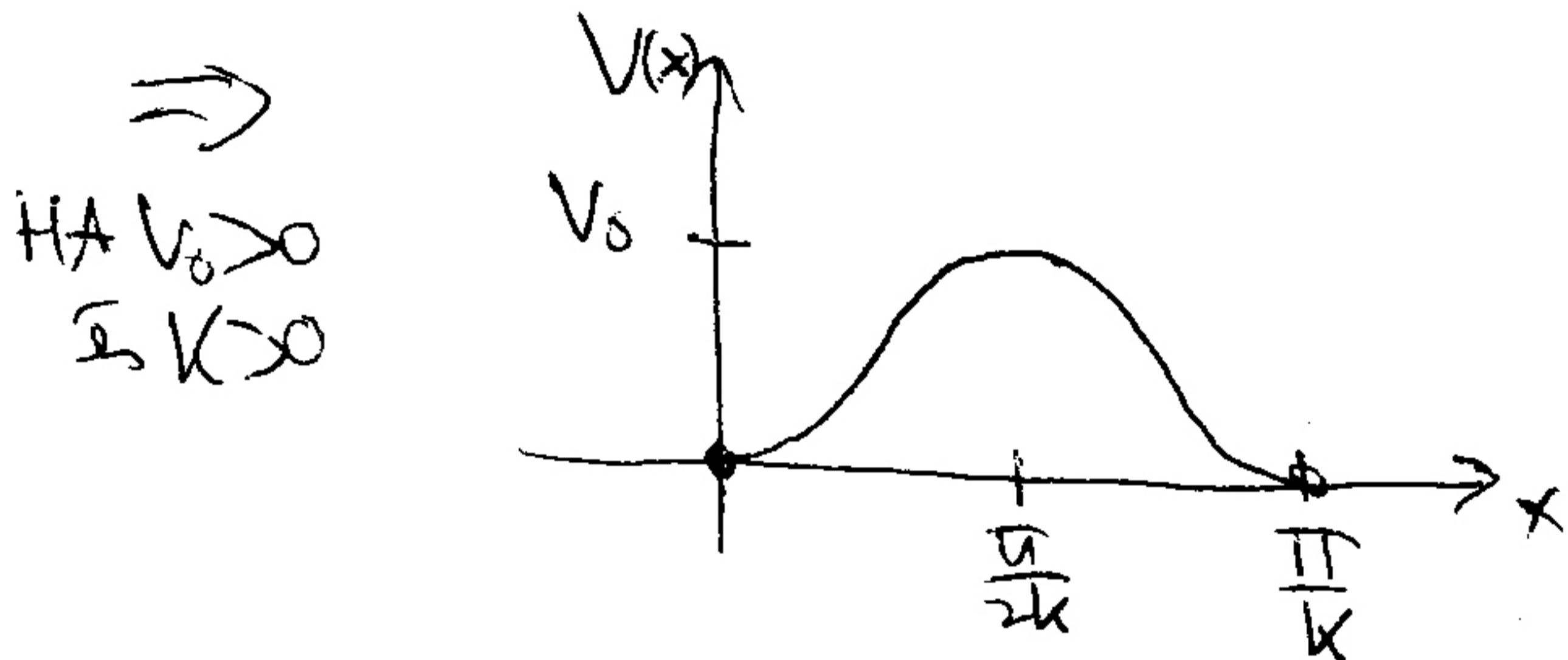
mivel $E + V_0 > 0$.

Csak felvő parabola lehet!

11.

$$V(x) = V_0 \sin^2(kx) = V_0 \frac{1 - \cos(2kx)}{2}$$

Az \cos „hullámhossza”: $\frac{2\pi}{2k} = \frac{\pi}{k}$, vagyis
 éppen az értelmezési tartomány vége felel meg
 az 1 periódusnak.



Ezenyi tájékozódást
 érdemes megtenni, azonban
 ez elég nem lesz
 a feladat megoldásához.

$$V'(x) = V_0 \cdot 2 \sin(kx) \cdot \cos(kx) \cdot k = V_0 \cdot k \cdot \sin(2kx)$$

$$V'(x)|_{x=x^*} = V_0 \cdot k \cdot \sin(2kx^*) = 0$$

$$\Rightarrow \sin(2kx^*) = 0$$

$$2kx_1^* = 2\pi m_1, m_1 \in \mathbb{Z}$$

$$x_1^* = \frac{2\pi m_1}{2k} = \frac{\pi}{k} m_1$$

Mivel $x \in [0, \frac{\pi}{k})$, csak
 az $m_1 = 0$ eset jó:

$$x_1^* = 0$$

$$2kx_2^* = \pi + 2\pi m_2, m_2 \in \mathbb{Z}$$

$$x_2^* = \frac{\pi + 2\pi m_2}{2k} =$$

$$= \frac{\pi}{2k} + \frac{\pi}{k} m_2$$

Csak $m_2 = 0$ jó:

$$x_2^* = \frac{\pi}{2k}$$

$$V''(x) = V_0 k \cos(2kx) \cdot 2k = 2V_0 k^2 \cos(2kx)$$

$$x_1^* : V''(x)|_{x=x_1^*} = 2V_0k^2 \underbrace{\cos(2k \cdot 0)}_{=1} = 2V_0k^2$$

$2V_0k^2 > 0$ akkor is csak akkor, ha $V_0 > 0$. Ebben az esetben lesz x_1^* stabil.

Ha x_1^* stabil, akkor a kis rezgés frekvenciája formalizusan:

$$\omega_1 = \sqrt{\frac{1}{m} V''(x)|_{x=x_1^*}} = \sqrt{\frac{2V_0k^2}{m}} = |k| \sqrt{\frac{2V_0}{m}}$$

De x_1^* az egyensúlyi tartományon belül van, ezt a kis rezgés valószínűleg kiegészítő a potenciál egyensúlyi tartományából.

Ha az egyensúlyi tartományt kiegészítjük, csak ebben az esetben valószínűleg meg tanulmányozzuk a kis rezgés.

$$x_2^* : V''(x)|_{x=x_2^*} = 2V_0k^2 \underbrace{\cos(2k \cdot \frac{\pi}{2k})}_{=-1} = -2V_0k^2$$

$-2V_0k^2 > 0$ akkor is csak akkor, ha $V_0 < 0$. Ebben x_2^* stabil.

Ha x_2^* stabil:

$$\omega_2 = \sqrt{\frac{1}{m} V''(x)|_{x=x_2^*}} = \sqrt{\frac{-2V_0k^2}{m}} = |k| \sqrt{\frac{2|V_0|}{m}}$$

12.

$$V'(x) = V_0 \left(-\frac{a}{(x+a)^2} + \frac{a}{(x-a)^2} \right)$$

$$V'(x)|_{x=x^*} = V_0 a \left(-\frac{1}{(x^*+a)^2} + \frac{1}{(x^*-a)^2} \right) = 0$$

$$\Rightarrow -\frac{1}{(x^*+a)^2} + \frac{1}{(x^*-a)^2} = 0$$

$$(x^*-a)^2 = (x^*+a)^2$$

$$x^*-a = x^*+a$$

$$-a = a \quad \downarrow$$

$$x^*-a = -(x^*+a)$$

$$x^* = 0 \quad \leftarrow \quad 2x^* = 0$$

$$V''(x) = V_0 \left(2 \frac{a}{(x+a)^3} - 2 \frac{a}{(x-a)^3} \right) = 2V_0 a \left(\frac{1}{(x+a)^3} - \frac{1}{(x-a)^3} \right)$$

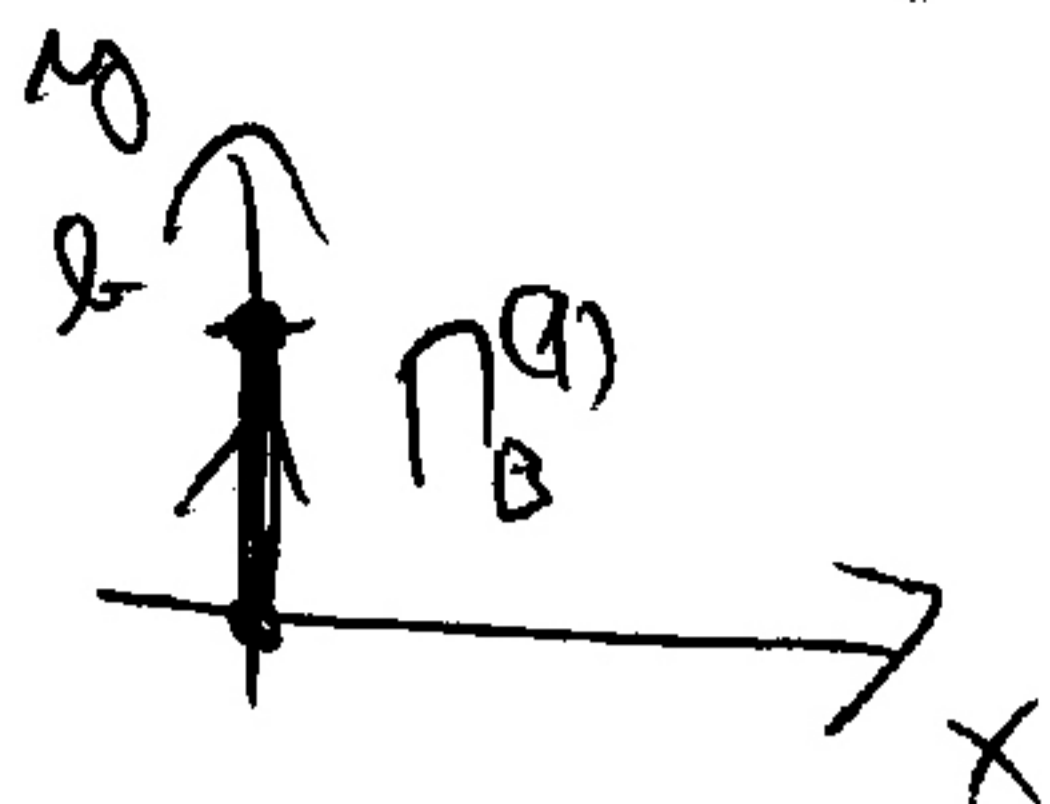
$$V''(x) \Big|_{x=x^*} = 2V_0 a \left(\frac{1}{(a+a)^3} - \frac{1}{(0-a)^3} \right) = 2V_0 a \left(\frac{1}{a^3} + \frac{1}{a^3} \right) =$$

$$= 4V_0 \frac{a}{a^3} = 4 \frac{V_0}{a^2} > 0 \Rightarrow x^* \text{ r\u00e9el lokalulb\u00e1t\u00f3r hely}$$

$$\omega = \sqrt{\frac{1}{m} V''(x) \Big|_{x=x^*}} = \sqrt{\frac{1}{m} 4 \frac{V_0}{a^2}} = 2 \frac{1}{a} \sqrt{\frac{V_0}{m}}$$

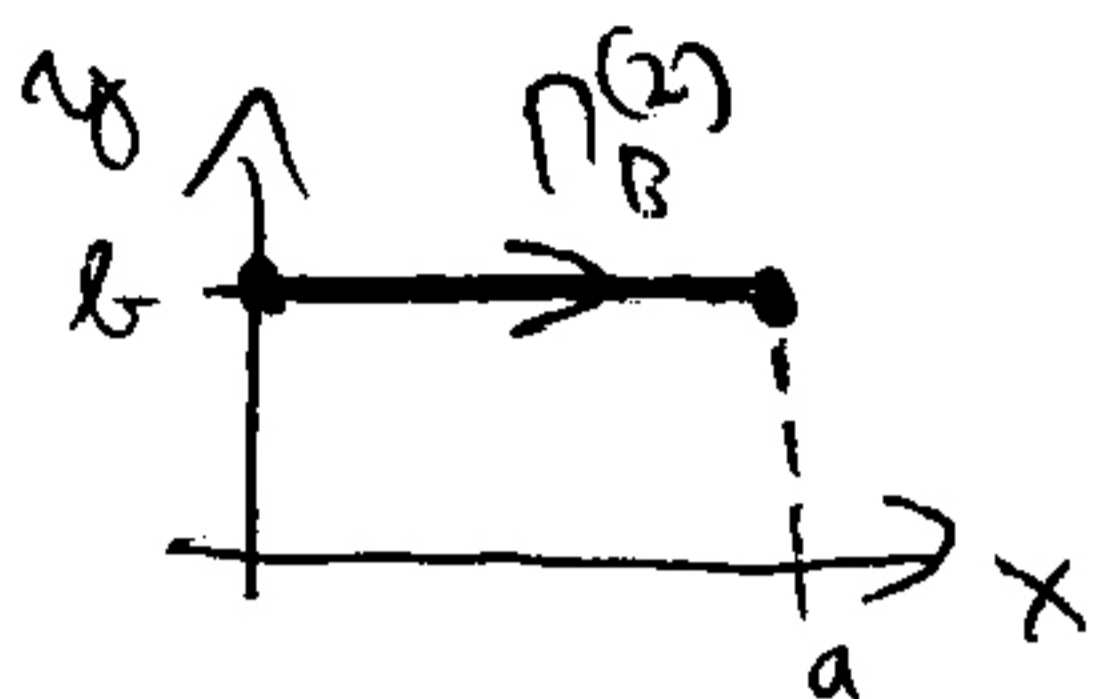
13.

EMB / Gy1 / 17



$$n_B^{(1)}: l=b, x=0, y=1, \underline{I} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\Psi_{n_B^{(1)}} = \int_0^b C \cdot 0^2 \cdot 1 \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} ds = 0$$



$$n_B^{(2)}: l=a, x=1, y=b, \underline{I} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

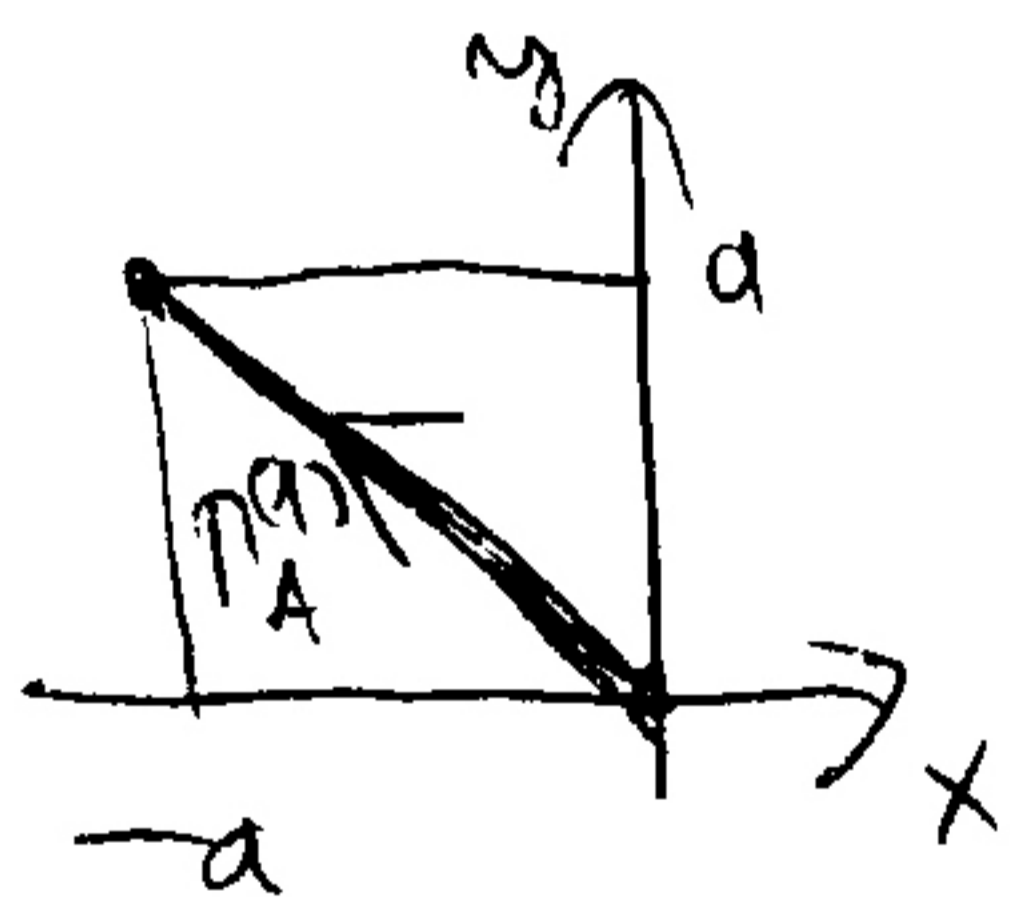
$$\Psi_{n_B^{(2)}} = \int_0^a C \cdot 1^2 \cdot b \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} ds =$$

$$= -1 \cdot 1 + 1 \cdot 0 = -1$$

$$= -\frac{1}{\sqrt{2}} C b \int_0^a 1^2 ds = -\frac{1}{3 \cdot \sqrt{2}} C a^3 b$$

$$\Psi_{n_B} = \Psi_{n_B^{(1)}} + \Psi_{n_B^{(2)}} = 0 - \frac{1}{3 \cdot \sqrt{2}} C a^3 b = -\frac{1}{3 \cdot \sqrt{2}} C a^3 b$$

14.



$$n_A^{(1)}: l = \sqrt{2}a$$

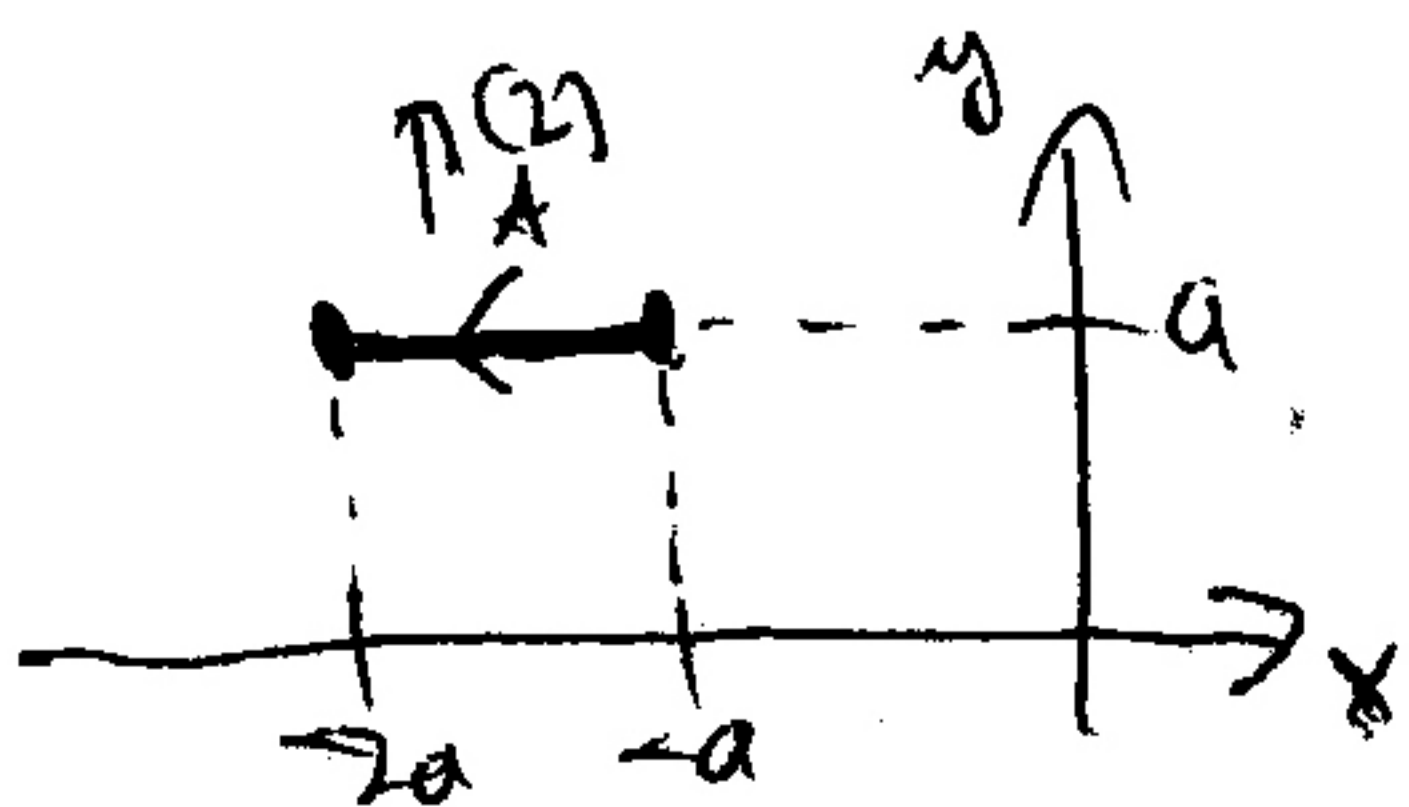
$$x = -s \cdot \cos 45^\circ = -\frac{s}{\sqrt{2}}$$

$$y = +s \cdot \sin 45^\circ = \frac{s}{\sqrt{2}}$$

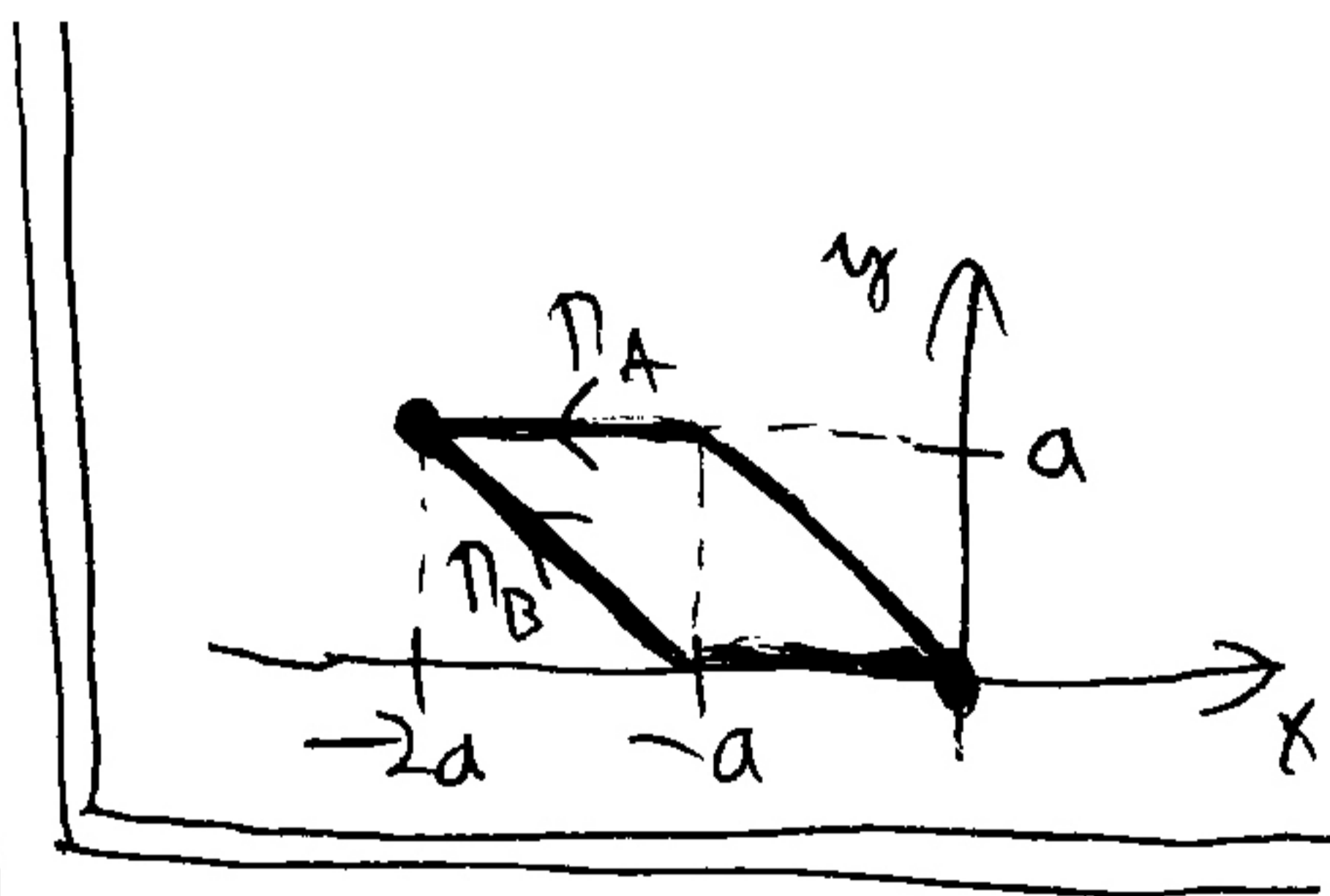
$$\underline{I} = \frac{d}{ds} \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\Psi_{n_A^{(1)}} = \int_0^{\sqrt{2}a} C \cdot \left(\frac{s}{\sqrt{2}}\right)^2 \cdot \left(\frac{1}{\sqrt{2}}\right)^2 \begin{pmatrix} -1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} ds = 0$$

$$= 1 \cdot (-1) + 1 \cdot 1 = 0$$

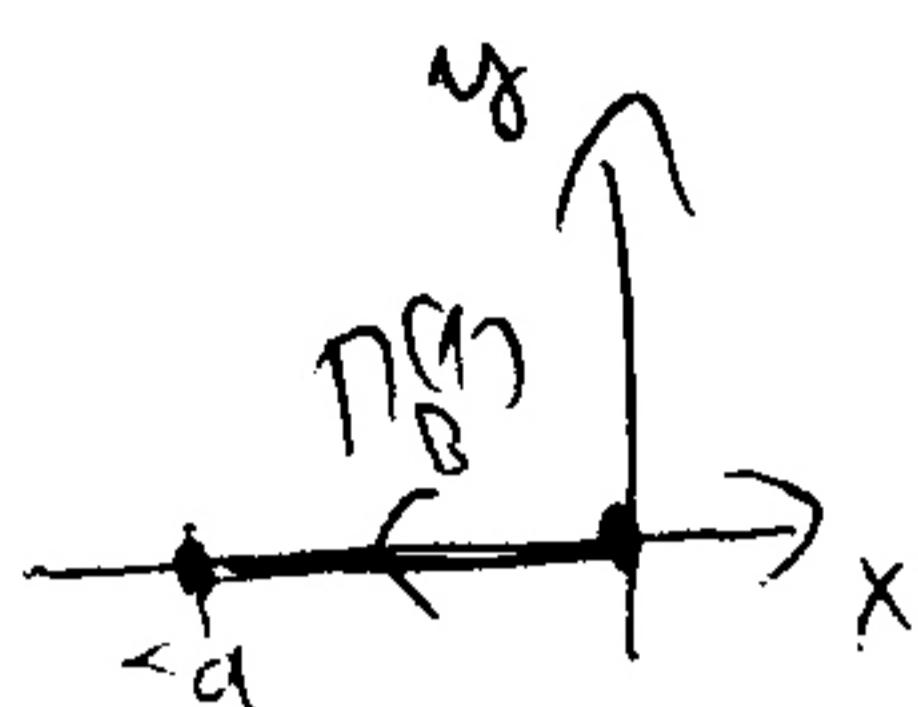


$$n_A^{(2)}: l=a, x=-a-s, y=a, \underline{I} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$



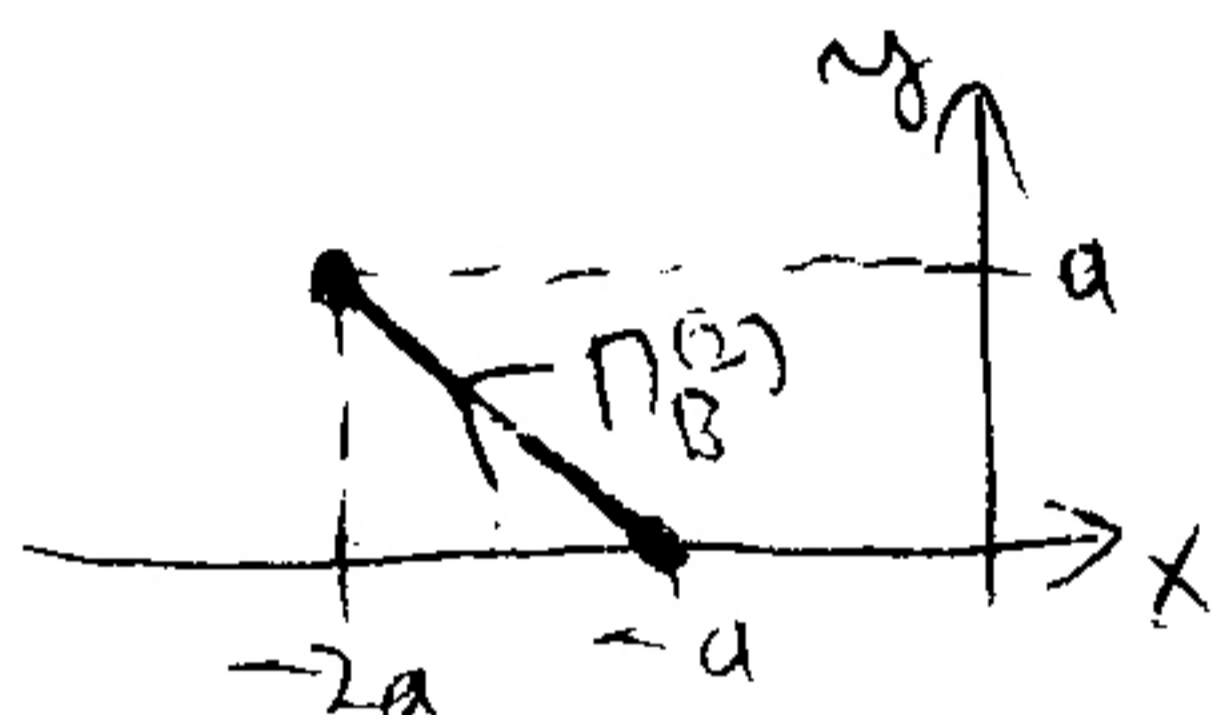
$$W_{n_A} = \int_0^a C \cdot a^2 \cdot \frac{1}{\sqrt{2}} \underbrace{(1 \cdot 1) \cdot (-1)}_{1 \cdot (-1) + 1 \cdot 0 = -1} ds = -\frac{1}{\sqrt{2}} C a^2 \int_0^a 1 ds = -\frac{1}{\sqrt{2}} C a^3$$

$$W_{n_A} = W_{n_A^{(1)}} + W_{n_A^{(2)}} = 0 - \frac{1}{\sqrt{2}} C a^3 = -\frac{1}{\sqrt{2}} C a^3$$



$$n_B^{(1)}: l = a, x = -a, y = 0, \underline{T} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$W_{n_B^{(1)}} = \int_0^a C \cdot 0^2 \cdot \frac{1}{\sqrt{2}} \underbrace{(1 \cdot 1) \cdot (-1)}_{1 \cdot (-1) + 1 \cdot 0 = -1} ds = 0$$



$$n_B^{(2)}: l = \sqrt{2} a, x = -a - 1 \cdot \cos 45^\circ = -a - \frac{1}{\sqrt{2}}$$

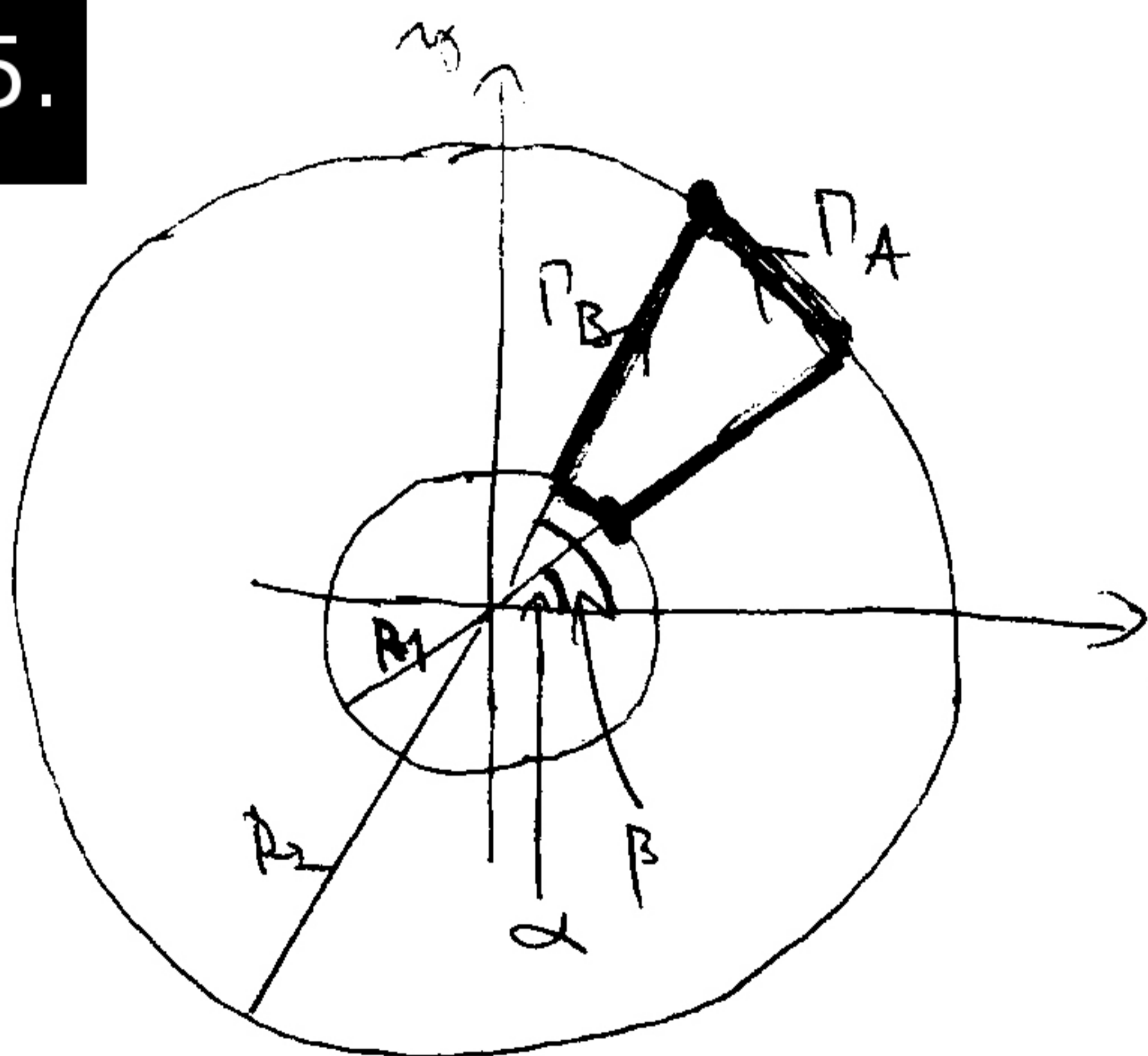
$$y = 1 \cdot \sin 45^\circ = \frac{1}{\sqrt{2}}, \underline{T} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$W_{n_B^{(2)}} = \int_0^{\sqrt{2}a} C \cdot \left(\frac{1}{\sqrt{2}}\right)^2 \underbrace{\left(\frac{1}{\sqrt{2}}\right)^2 (1 \cdot 1) \cdot (-1)}_{1 \cdot (-1) + 1 \cdot 1 = 0} ds = 0$$

$$W_{n_B} = W_{n_B^{(1)}} + W_{n_B^{(2)}} = 0 + 0 = 0$$

$W_{n_B} \neq W_{n_A} \Rightarrow$ Az erő nem lehet konzervatív.

15.



Az erő körpályát kísérő az

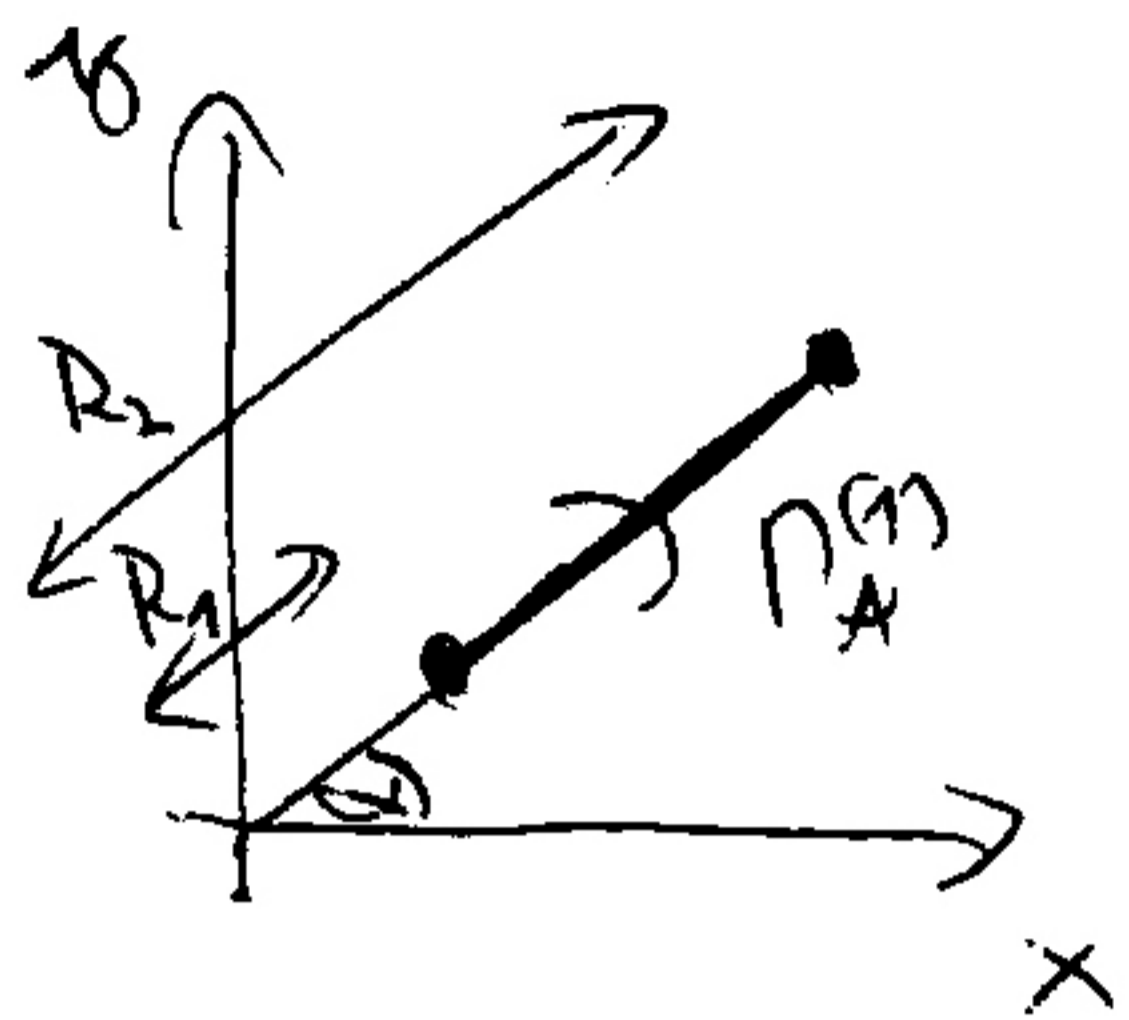
$$\underline{v} = v \underline{e}_\varphi$$

körpály sebességével átalakítani:

$$\underline{F}(\underline{r}) = 4\epsilon \left[12 \left(\frac{r}{v}\right)^{12} - 6 \left(\frac{r^3}{v}\right) \right] \frac{v \underline{e}_\varphi}{v^2} =$$

$$= 4\epsilon \left[12 \left(\frac{r}{v}\right)^{12} - \left(\frac{r^3}{v}\right)^6 \right] \frac{1}{v} \underline{e}_\varphi =$$

$$= 4\epsilon \left(12 \frac{\sigma^{12}}{r^{13}} - 6 \frac{\sigma^6}{r^7} \right) \underline{e}_v$$



$$P_A^{(1)}: l = R_2 - R_1, \quad v = R_1 + s, \quad \psi = \alpha, \quad \underline{I} = \underline{e}_v$$

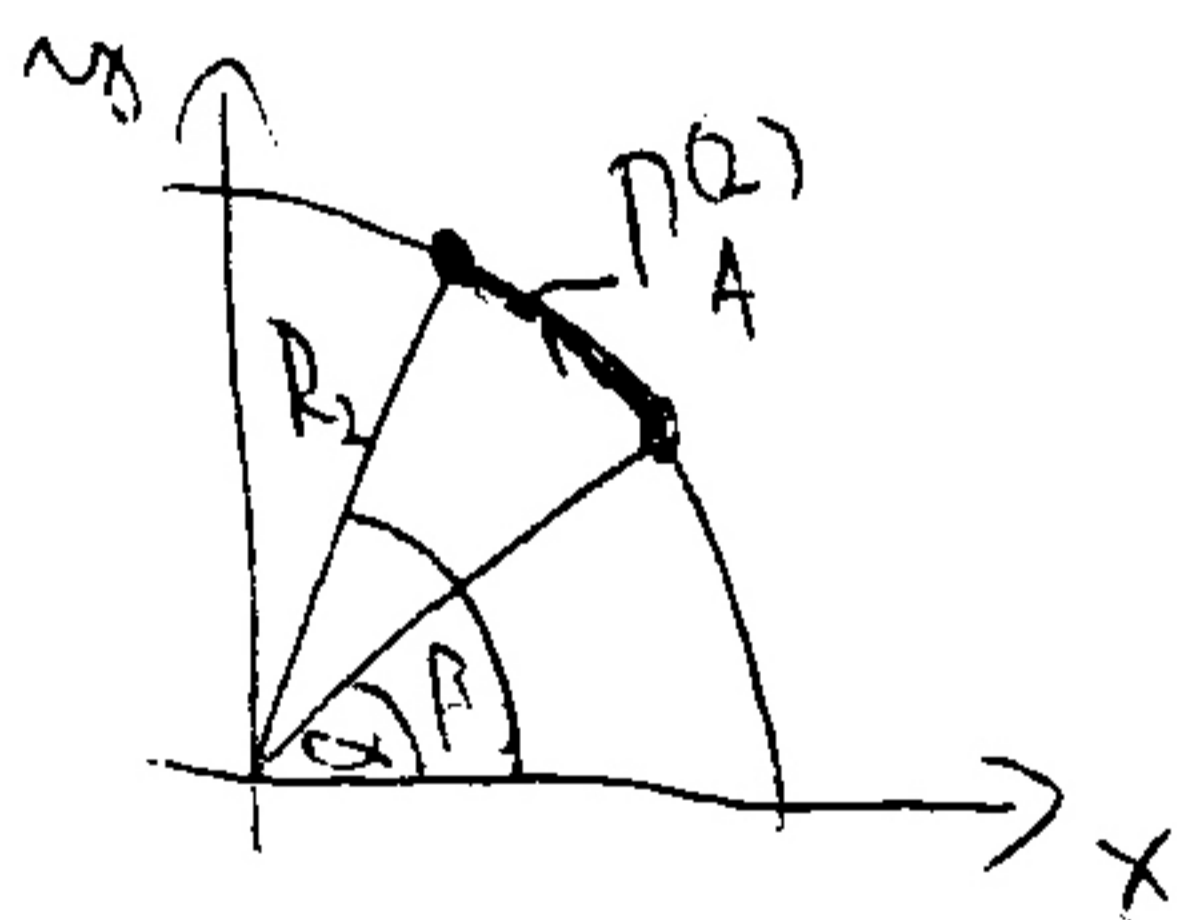
$$W_{P_A^{(1)}} = \int_0^{R_2 - R_1} 4\epsilon \left(12 \frac{\sigma^{12}}{(R_1 + s)^{13}} - 6 \frac{\sigma^6}{(R_1 + s)^7} \right) \underbrace{\underline{e}_v \underline{e}_v}_{=1} ds =$$

$$= \left[4\epsilon \left(12 \sigma^{12} \frac{(R_1 + s)^{-12}}{-12} - 6 \sigma^6 \frac{(R_1 + s)^{-6}}{-6} \right) \right]_0^{R_2 - R_1} =$$

$$= 4\epsilon \left(-\sigma^{12} (R_1 + R_2 - R_1)^{-12} + \sigma^6 (R_1 + R_2 - R_1)^{-6} \right) -$$

$$- 4\epsilon \left(-\sigma^{12} (R_1 + 0)^{-12} + \sigma^6 (R_1 + 0)^{-6} \right) =$$

$$= 4\epsilon \left(-\sigma^{12} \left(\frac{1}{R_2^{12}} - \frac{1}{R_1^{12}} \right) + \sigma^6 \left(\frac{1}{R_2^6} - \frac{1}{R_1^6} \right) \right)$$



$$P_A^{(2)}: l = (\beta - \alpha) R_2 \quad (\text{L\u00e4nge B\u00f6ge} = \text{Winkel} \cdot \text{Radius}),$$

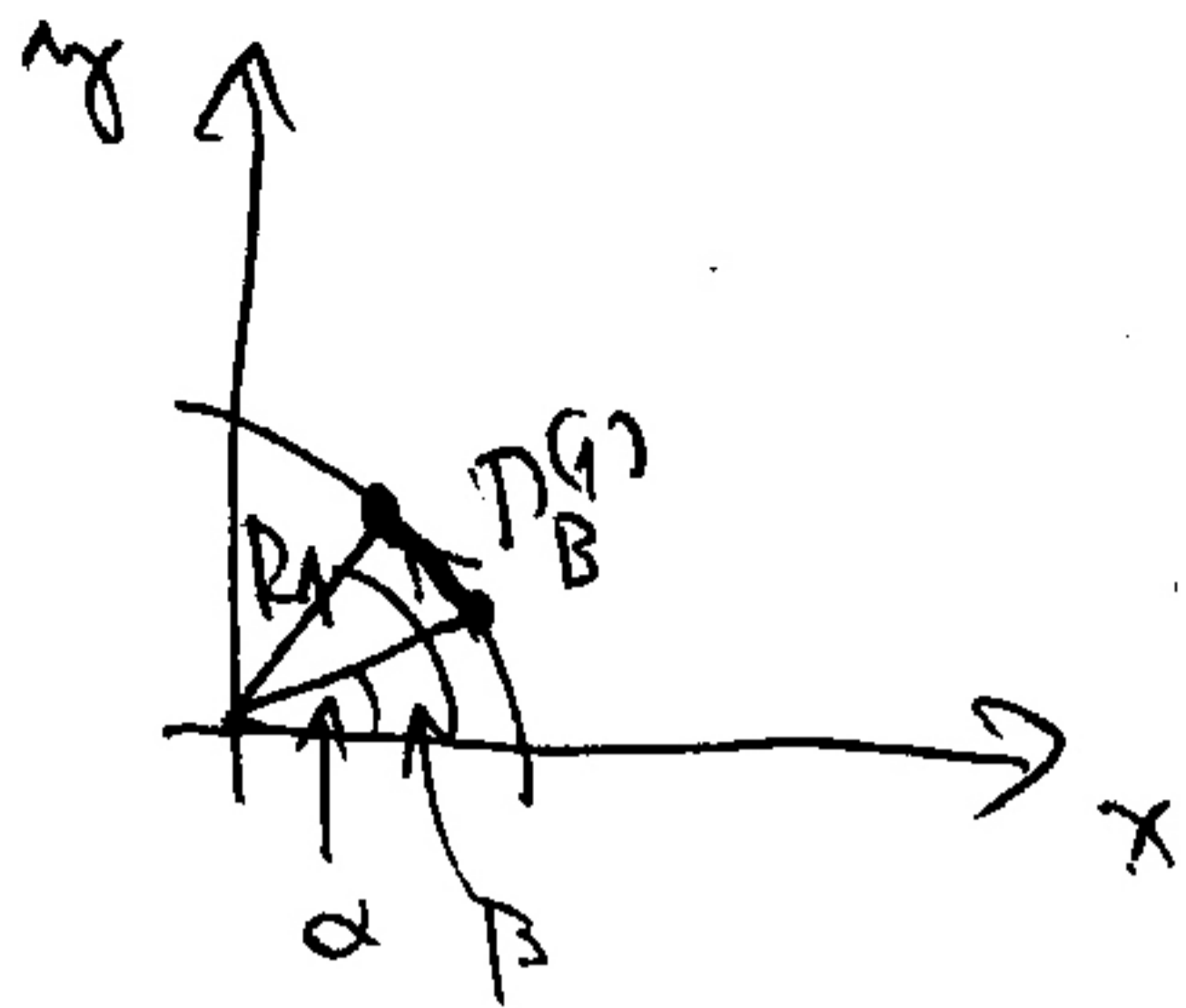
$$v = R_2, \quad \psi = \alpha + \frac{s}{R_2} \quad (\text{Winkel} = \frac{\text{L\u00e4nge B\u00f6ge}}{\text{Radius}}),$$

$$\underline{I} = \underline{e}_\psi$$

$$W_{P_A^{(2)}} = \int_0^{(\beta - \alpha) R_2} 4\epsilon \left(12 \frac{\sigma^{12}}{R_2^{13}} - 6 \frac{\sigma^6}{R_2^7} \right) \underbrace{\underline{e}_v \underline{e}_\psi}_{=0} ds = 0$$

$$W_{P_A} = W_{P_A^{(1)}} + W_{P_A^{(2)}} = W_{P_A^{(1)}} + 0 = W_{P_A^{(1)}} =$$

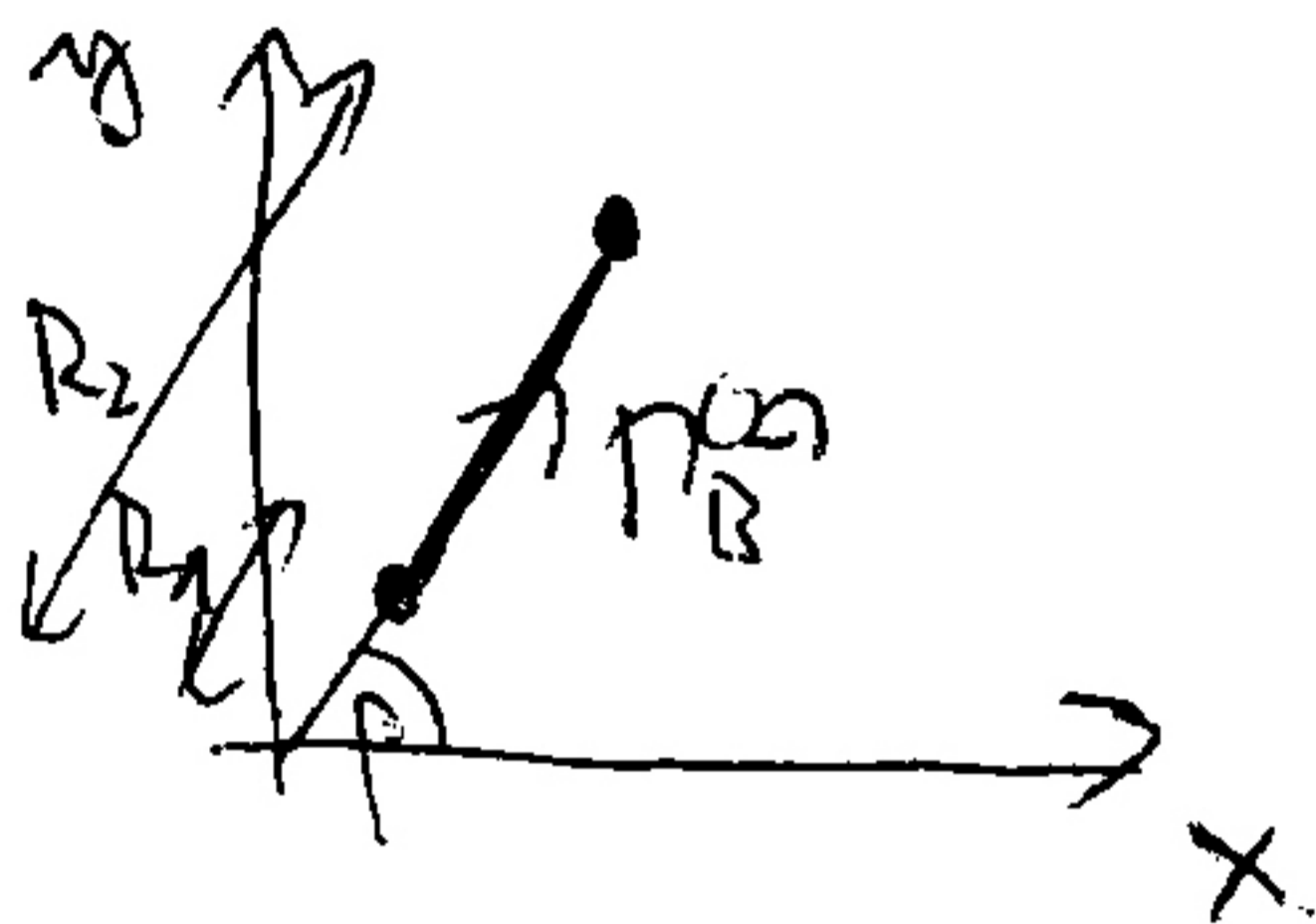
$$= 4\epsilon \left(\sigma^6 \left(\frac{1}{R_2^6} - \frac{1}{R_1^6} \right) - \sigma^{12} \left(\frac{1}{R_2^{12}} - \frac{1}{R_1^{12}} \right) \right)$$



$$\pi_B^{(1)}: l = (\beta - \alpha) \cdot R_1, \quad r = R_1, \quad \varphi = \alpha + \frac{s}{R_1}$$

$$I = \underline{e} \varphi$$

$$\mathcal{W}_{\pi_B^{(1)}} = \int_0^{(\beta - \alpha) R_1} 4\epsilon \left(12 \frac{\sigma^{12}}{R_1^{13}} - 6 \frac{\sigma^6}{R_1^7} \right) \underbrace{\underline{e} v \underline{e} \varphi}_{=0} ds = 0$$



$$\pi_B^{(2)}: l = R_2 - R_1, \quad r = R_1 + s, \quad \varphi = \beta, \quad I = \underline{e} v$$

↳ ezt az eldöntve $\pi_B^{(2)}$ paraméterese megfogadjuk $\pi_A^{(1)}$ paraméteresével.

Mivel \mathcal{W} -t ebben a feladatban nem használjuk fel a munka kiszámításra, ezért:

$$\mathcal{W}_{\pi_B^{(2)}} = \mathcal{W}_{\pi_A^{(1)}}$$

$$\mathcal{W}_{\pi_B} = \mathcal{W}_{\pi_B^{(1)}} + \mathcal{W}_{\pi_B^{(2)}} = 0 + \mathcal{W}_{\pi_A^{(1)}} = \mathcal{W}_{\pi_A^{(1)}} = \mathcal{W}_{\pi_A} =$$

$$= 4\epsilon \left(\sigma^6 \left(\frac{1}{R_2^7} - \frac{1}{R_1^7} \right) - \sigma^{12} \left(\frac{1}{R_2^{13}} - \frac{1}{R_1^{13}} \right) \right)$$

$\mathcal{W}_{\pi_B} = \mathcal{W}_{\pi_A} \Rightarrow$ lehet potenciál, az előbbi ldet konseratív.

(Az eredmény alapján nem tudjuk eldönteni, hogy konseratív-e, ugyanis csak 2 konkrét görbét vizsgáltunk.)